

SOLUTIONS

LEVEL – I

1. $w = \frac{2\pi}{T}$ as time period is some $\frac{W_1}{W_2} = 1$

2. Centripetal acc. $(a_c) = \frac{v^2}{R}$

Tangential acc. $a_t = a$

$$\begin{aligned}\text{Net acc. } a &= \sqrt{a_c^2 + a_t^2} = \sqrt{\frac{v^4}{R^2} + a^2} \\ &= \sqrt{\frac{(30)^4}{(500)^2} + 2^2} = 2.7 \text{ m/s}^2\end{aligned}$$

3. It becomes null

4. Velocity and acceleration both changes

5. Magnitude of acceleration remains constant.

6. Path will be parabola

7. Velocity vector and acceleration vector are perpendicular to each other

8. Acceleration of the particle $a_c = W^2 R = (2\pi v)^2 R$

9. Angular velocity $W_{P/A} = \frac{v}{2r}$

$$\& \quad w_{p/o} = \frac{v}{r}$$

10. Centripetal acceleration $a_c = \frac{v^2}{R}$

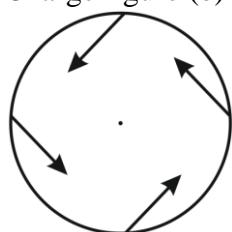
Tangential acceleration $a_t = a$

$$\text{Net acceleration} = \sqrt{\left(\frac{v^2}{R}\right)^2 + a^2}$$

11. Magnitude & direction of acceleration both changes.

12. Speed remain const.

13. Charge figure (b)



14. $N = mg - \frac{mv^2}{R}$, when train moves from east to west relative velocity increases & hence N decreases.

15. Acceleration $a_c = w^2 r$

16. There is no change in angular velocity as it is an axial vector.

17. Net acceleration

$$a = \sqrt{a_c^2 + a_f^2}$$

$$a_c = \frac{v^2}{R} \text{ & } a_t = a$$

18. $a_c = w^2 R$ $w = 2\pi r$

19. Displacement = 0

$$\text{Distance} = 2R + \frac{2\pi R}{4} = 2 + \frac{\pi}{2}$$

$$\text{Average speed} = \frac{\frac{2 + \frac{\pi}{2}}{10}}{60} = 3(\pi + 4)$$

20. Displacement = $2r \sin \theta / 2$

$$a_c = \frac{v^2}{R}$$

22. $w = 2\pi r$ and $v = rw$

23. Displacement = $2r \sin(\theta/2)$

$$x = a(1 - \cos \omega t), y = a \sin \omega t$$

24. $x = a - a \cos \omega t,$

$$\text{or } (x - a) = -a \cos \omega t \text{ & } y = a \sin \omega t$$

Square and add

$$(x - a)^2 + y^2 = a^2$$

25. Position vector $\vec{r} = (2t\hat{i} + 2t^2\hat{j}) \text{ m}$

$$\text{Velocity vector } \vec{v} = \frac{d\vec{r}}{dt} = (2\hat{i} + 4t\hat{j}) \text{ m/s}$$

Velocity at $t = 2 \text{ sec.}$

$$\vec{v} = (2\hat{i} + 8\hat{j}) \text{ m/s} \text{ & } |\vec{v}| = \sqrt{4 + 64} = 2\sqrt{17} \text{ m/s}$$

Angle made by velocity with x – axis

$$\tan \theta = \frac{v_y}{v_x} = \frac{4t}{2} = 2t$$

Differentiate w.r.t.t

$$\sec^2 \theta \frac{d\theta}{dt} = 2 \Rightarrow \frac{d\theta}{dt} = 2 \cos^2 \theta$$

$$\text{or } \frac{d\theta}{dt} = 2 \times \left(\frac{2}{2\sqrt{17}} \right)^2 = \frac{2}{17} \text{ Rad/sec}$$

26.

$$a_c = \frac{v^2}{R} \text{ or } R = \frac{v^2}{a_c} = \frac{(8 \sin 30)^2}{2} = 8 \text{ m}$$

27. Avg ace = $\frac{\Delta V}{t}$ $\Delta V = 2V$

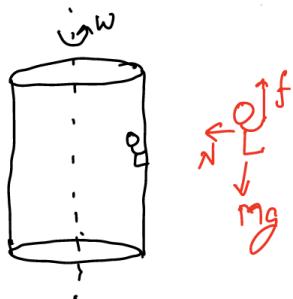
$$\text{& } t = \frac{\pi R}{v}$$

28. Net acceleration $a = \sqrt{a_c^2 + a_f^2}$

29. Net acceleration $a = \sqrt{a_c^2 + G_f^2}$
 30. Kinetic Energy remains constant.

31. $N = mg - \frac{mv^2}{R}$
 $R_B > R_A$ so $N_B > N_A$
 32. Work done = $F S \cos \theta$
 As $\theta = 90^\circ$, so $w = 0$

33.



$$N = m\omega^2 R$$

Friction force $f = \mu N = mg$

$$\mu m\omega^2 R = mg$$

$$\omega_{\min} = \sqrt{\frac{g}{\mu R}}$$

34. Required centripetal force

$$f_c = m\omega^2 \times 4r = \mu mg$$

$$\text{When } \omega' = 2\omega$$

$$m(2\omega)^2 \times r' = \mu mg$$

On solving $r' = r$

35. Tension $T = mw^2 r$
 If tension becomes $2T$, keeping r const
 $2T = 2w'^2 r$

$$\Rightarrow w' = \sqrt{2}w = 7 \text{ rpm}$$

36. Speed remains constant and hence KE.

37. Max. allowed speed $v = \sqrt{\mu g R}$

38. centripetal force = $\frac{mv^2}{R}$ towards centre

39. Tension $T = mw^2 r$

40. Required centripetal force will be given by friction between tyre and the road.

41. $N = mg - \frac{mV^2}{R}$ compare R

42. Actual forces are mg & T

43. friction force $f = \mu N = \mu m(L \propto) = \mu mL \propto$

Required centripetal force $f = mw^2 L = \mu mL \propto$

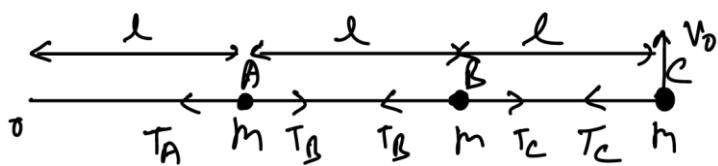
$$w^2 = \mu \propto \Rightarrow w \sqrt{\mu} \propto$$

$$\omega = \omega_r + \alpha t$$

$$\sqrt{\mu \alpha} = 0 + \alpha t \Rightarrow t_2 \sqrt{\frac{\mu}{\alpha}}$$

PYQ

1. Kinetic energy remains constant.
2. Inner wheel leaves the ground first
3. Acceleration $a = \omega^2 R$, $\omega = 2\pi r$
4. Centripetal force
5. Momentum changes by $= \Delta P = mv - (-mv)$
 $= 2mv$
6. Force and displacement are perpendicular to each other
7. Acceleration in towards centre
8. Tangential acceleration is 300
9. $a_c = \frac{v^2}{R}$
10. Average speed = $\frac{\text{total distance}}{\text{total time}}$
11. Linear velocity $v = rw$, acceleration $= \omega^2 R$
Tension $T = mw^2 R$
12. Acceleration $a_c = \frac{v^2}{R}$
13. $v\sqrt{\mu g R}$
14. $F = \frac{mv^2}{R}$
15. $F = mw^2 R$, $w = \frac{2\pi}{T}$
16. Momentum
- 17.

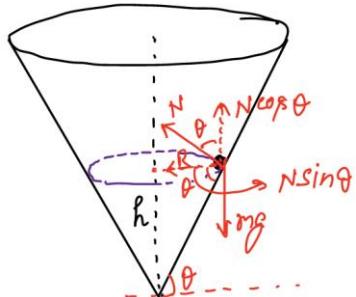


$$\omega = \frac{v_o}{3l} \text{ Centripetal force on C, } T_c = mw^2(3l)$$

$$\text{For particle B, } T_B - T_C = mw^2(2l)$$

$$\text{For particle A, } T_A - T_B = mw^2 l$$

18.



$$N \cos \theta = Mg \quad \dots(1)$$

$$N \sin \theta = \frac{mv^2}{R} \quad \dots(2)$$

Divide(2) / (1)

$$\tan \theta = \frac{v^2}{Rg} = \frac{h}{R}$$

$$\text{Or } h = \frac{v^2}{g}$$

19. Angular velocity $w = \frac{2\pi}{T}$
 $T = 24 \text{ hrs} = 24 \times 60 \times 60 \text{ sec}$

20. Angular velocity $w = \frac{2\pi}{T}$

Linear velocity $v = \ell w$

21. Min speed at top $= \sqrt{gR}$

$$w = \frac{v}{R} = \sqrt{g/R}$$

$$T = \frac{2\pi}{w} = 4 \text{ sec}$$

22. $a = \sqrt{a_c^2 + a_f^2}$, $a_c = \frac{v^2}{R}$, $at = 9 = 2m/s^2$

23. $v = \sqrt{5gl}$

24. min velocity at the highest point $= \sqrt{gr}$

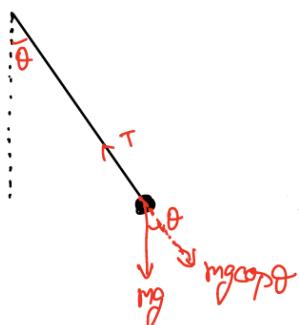
25. $T = mg + mw^2R$ $w = 2\pi r$ & $r = \frac{n}{40}$

26. To complete circular turn, min speed at lowest point $v = \sqrt{5gR}$
 Apply conservation of mechanical energy.

$$mgh = \frac{1}{2}mv^2 \Rightarrow v = \sqrt{2gh} = \sqrt{5gR}$$

$$R = \frac{2h}{5} = \frac{2 \times 5}{5} = 2m$$

27.



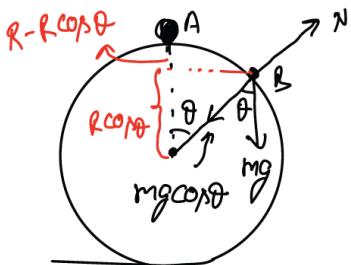
$$T - mg \cos \theta = \frac{mv^2}{R}$$

$$T = mg \cos \theta + \frac{mv^2}{R}$$

28. $mg \cos \theta - N = \frac{mv^2}{R}$

When particle reaves the surface, $N = 0$

$$V = \sqrt{gR \cos \theta}$$



Apply ME conservation at A & B

$$ME_A = ME_B$$

$$O = \frac{1}{2} mv^2 - mgR(1 - \cos \theta)$$

$$\text{Or } V = \sqrt{2gR(1 - \cos \theta)}$$

$$= \sqrt{gR \cos \theta}$$

OR

$$2gR(1 - \cos \theta) = gR \cos \theta$$

$$2 - 2 \cos \theta = \cos \theta \Rightarrow 2 = 3 \cos \theta$$

$$\text{or } \cos \theta = \frac{2}{3}$$

$$\text{Height from ground } h = R + R \cos \theta = R(1 + \cos \theta)$$

29. $v_x = \frac{dx}{dt} = 3at^2 \text{ & } v_y = \frac{dy}{dt} = 3bt^2$

$$\text{Net speed } V = \sqrt{V_x^2 + V_y^2}$$

30. $\vec{\Delta V} = \vec{V}_2 - \vec{V}_1$

$$|\vec{\Delta V}| = \sqrt{V^2 + V^2} = V\sqrt{2}$$

31. Required centripetal force $f_c = \frac{mv^2}{R} = \mu mg$

$$\text{Or } v = \sqrt{\mu g R}$$

32. $\vec{R} = 4 \sin(2\pi t) \hat{i} + 4 \cos(2\pi t) \hat{j}$

$$x = 4 \sin 2\pi t, y = 4 \cos 2\pi t$$

Square and add

$$x^2 + y^2 = 4^2$$

$$\vec{V} = \frac{d\vec{R}}{dt} = 8\pi \cos 2\pi t \hat{i} - 8\pi \sin 2\pi t \hat{j}$$

$$\begin{aligned}\text{Acceleration } \vec{a} &= \frac{d\vec{V}}{dt} = -16\pi^2 \sin 2\pi t \hat{i} - 16\pi^2 \cos 2\pi t \hat{j} \\ &= 4\pi^2 (4 \sin 2\pi t \hat{i} + 4 \cos 2\pi t \hat{j}) \\ &= -4\pi^2 \vec{R}\end{aligned}$$

33. $\sqrt{gR \frac{\mu_s + \tan \theta}{1 - \mu_s \tan \theta}}$

34. $\vec{r} = \cos \omega t \hat{x} + \sin \omega t \hat{y}$

$$\vec{v} = \frac{d\vec{r}}{dt} = -w \sin \omega t \hat{x} + w \cos \omega t \hat{y}$$

$$\vec{a} = \frac{d\vec{v}}{dt} = -\omega^2 \cos \omega t \hat{x} - \omega^2 \sin \omega t \hat{y}$$

& $= -\omega^2 (\cos \omega t \hat{x} + \sin \omega t \hat{y}) = -\omega^2 \vec{r}$
 $\vec{v} \cdot \vec{r} = 0$

35. min speed at lowest point $= \sqrt{5gR}$

$$KE = \frac{1}{2} mv^2 = 8 \times 10^{-1} J$$

36. $\Rightarrow \frac{1}{2} \times 10 \times 10^{-3} \times V^2 = 8 \times 10^{-1}$

$$V^2 = \frac{16 \times 10^{-1}}{10^{-2}} = 160 \Rightarrow v = \sqrt{160} M/R$$

$$\text{So, } a_c = \frac{v^2}{R}$$

To find technical acc.

$$v^2 = 4\alpha f a s$$

$$160 = 0 f \alpha \times 2 \times 2\pi R$$

$$\text{find } a, \text{ then } a = \sqrt{a_c^2 + a^2}$$

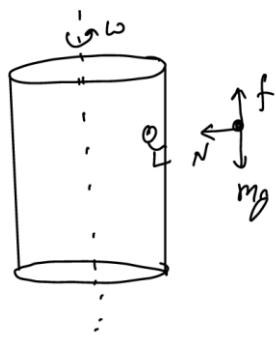
37. Acceleration towards centre

$$a \cos 30^\circ = \frac{v^2}{R}$$

$$15 \times \frac{\sqrt{3}}{2} = \frac{v^2}{2.5}$$

38. net force = T

39.



$$N = mw^2 R$$

$$f = \mu N = \mu mw^2 R = mg$$

$$w = \sqrt{\frac{g}{\mu R}}$$

40.

Given, the radius of the circular path = R

The time taken by the particle to complete one revolution = T

When the particle is projected with the same speed (by which it is moving in circular orbit) at angle θ to the horizontal, the maximum height attained it is given as

$$H_{\max} = \frac{u^2 \sin^2 \theta}{2g} \quad \dots(i)$$

$$H_{\max} = 4R \quad (\text{given})$$

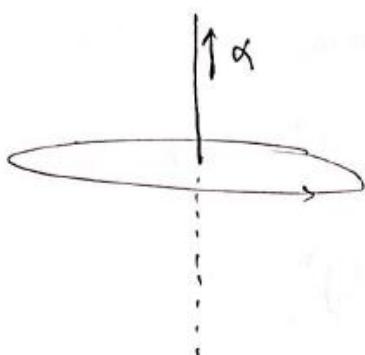
Also, we know that,
speed of the particle in circular path,

$$u = \frac{2\pi R}{T}$$

Substituting the values in the Eq. (i), we get

$$\begin{aligned} 4R &= \frac{\left(\frac{2\pi R}{T}\right)^2 \sin^2 \theta}{2g} \\ \Rightarrow \quad \sin \theta &= \left(\frac{2gT^2}{\pi^2 R}\right)^{1/2} \\ \Rightarrow \quad \theta &= \sin^{-1} \left(\frac{2gT^2}{\pi^2 R}\right)^{1/2} \end{aligned}$$

41.



Angular acceleration
is axial vector.