

Inchapter Exercise

1. $\theta = 45^\circ$

Let two forces be \vec{F}_1 and \vec{F}_2 , $|\vec{F}_1| = F_1 = 2F$, $|\vec{F}_2| = F_2 = F\sqrt{2}$

Let angle between them be $\theta = ?$

Let $\vec{F}_R = \vec{F}_1 + \vec{F}_2$

$$\Rightarrow |\vec{F}_R| = \sqrt{F_1^2 + F_2^2 + 2F_1F_2 \cos \theta}$$

$$\text{Given } F_R = F\sqrt{10} = \sqrt{(2F)^2 + (F\sqrt{2})^2 + 2(2F)(F\sqrt{2})\cos \theta}$$

$$F\sqrt{10} = \sqrt{4F^2 + 2F^2 + 4F^2\sqrt{2}\cos \theta}$$

Squaring both sides

$$(F\sqrt{10})^2 = 4F^2 + 2F^2 + 4F^2\sqrt{2}\cos \theta$$

$$\Rightarrow 10F^2 = 6F^2 + 4F^2\sqrt{2}\cos \theta$$

$$\Rightarrow \cos \theta = \frac{1}{\sqrt{2}} \Rightarrow \theta = 45^\circ$$

2. **30 N, 40 B**

Let force be $\vec{F}_1, |\vec{F}_1| = F_1, \vec{F}_2, |\vec{F}_2| = F_2$

Let $F_1 > F_2$

Case - 1 \vec{F}_1 oppo. to \vec{F}_2

$$\text{ie if } \left. \begin{array}{l} \vec{F}_1 \rightarrow \\ \vec{F}_2 \leftarrow \end{array} \right\} \theta = 180^\circ$$

$$|\vec{F}_1 + \vec{F}_2| = \sqrt{F_1^2 + F_2^2 + 2F_1F_2 \cos 180^\circ}$$

Case 1

$$\downarrow \sqrt{F_1^2 + F_2^2 + 2F_1F_2(-1)}$$

$$10N = \sqrt{(F_1 - F_2)^2} = F_1 - F_2 \text{ (as } F_1 > F_2)$$

$$\Rightarrow F_1 - F_2 = 10N \quad \dots\dots(1)$$

Case - 2 - $\vec{F}_1 \perp^r$ to \vec{F}_2 i.e $\theta = 90^\circ$

$$\Rightarrow |\vec{F}_1 + \vec{F}_2| = \sqrt{F_1^2 + F_2^2 + 2F_1F_2 \cos 90^\circ}$$

\downarrow
 $= 0$

$$\text{So } = \sqrt{F_1^2 + F_2^2}$$

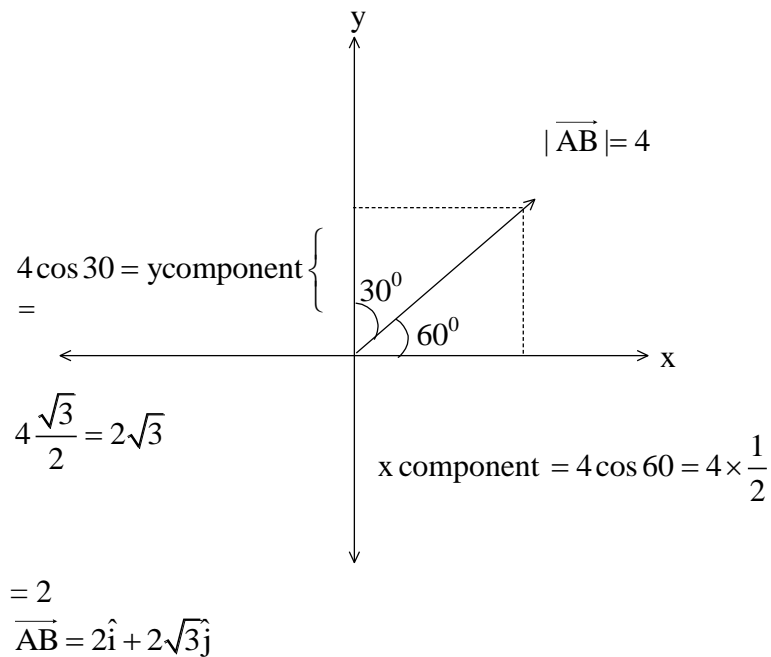
Squaring both sides

$$(50)^2 = F_1^2 + F_2^2 \text{ or } F_1^2 + F_2^2 = 2500 \quad \dots\dots(2)$$

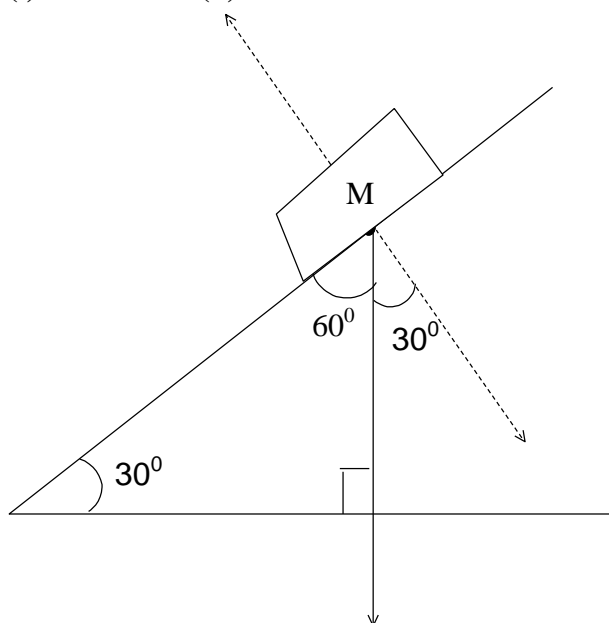
Solve equation (1) and (2) to get F_1 and F_2

Inchapter Exercise

1. $|\vec{AB}| = 4, \theta_x = 60^\circ$ and \vec{AB} lies in 1st quadrant.



2. (i) 500 N (ii) 866 N



$w = \text{weight} = 1000\text{N}$

Component in direction to plane $\parallel = 1000 \cos 60 = 500$

Component in direction $\perp = 1000 \cos 30 = 500\sqrt{3}$ to plane.

3. $2\vec{A} - 3\vec{B} = (4\hat{i} + 2\hat{j}) - (9\hat{j} - 3\hat{k})$

$$\vec{A} = 2\hat{i} + \hat{j}, \vec{B} = 3\hat{j} - \hat{k}$$

$$\Rightarrow 2\vec{A} = 4\hat{i} + 2\hat{j}$$

$$\Rightarrow 3\vec{B} = 9\hat{j} - 3\hat{k}$$

$$\begin{aligned}\text{Hence } 2\vec{A} - 3\vec{B} &= (4\hat{i} + 2\hat{j}) - (9\hat{j} - 3\hat{k}) \\ &= 4\hat{i} - 7\hat{j} + 3\hat{k}\end{aligned}$$

Inchapter Exercise

1. $\theta = 30^\circ$

$$\left. \begin{aligned}\vec{A} &= 2\hat{i} + \hat{j} - \hat{k} \\ \vec{B} &= \hat{i} - \hat{k}\end{aligned} \right\} \theta = ?$$

$$\begin{aligned}\cos \theta &= \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} = \frac{(2+1)}{\sqrt{2^2+1^2+1^2} \sqrt{2}} \\ &= \frac{3}{\sqrt{12}} = \frac{3}{2\sqrt{3}} = \frac{(\sqrt{3})(\sqrt{3})}{2\sqrt{3}}\end{aligned}$$

$$\cos \theta = \frac{\sqrt{3}}{2} \Rightarrow \theta = 30^\circ$$

2. $m = 3/14$

$$\left. \begin{aligned}\vec{A} &= 4\hat{i} + \hat{j} - 3\hat{k} \\ \vec{B} &= 2m\hat{i} + 6m\hat{j} + \hat{k}\end{aligned} \right\} \vec{A} \perp \vec{B} \text{ given}$$

$$\Rightarrow \vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos 90 = 0$$

$$\Rightarrow 8m + 6m - 3 = 0$$

$$\Rightarrow m = \frac{3}{14}$$

3. $\cos \theta = \frac{1}{\sqrt{3}}$

$$\left. \begin{aligned}\vec{A} &= \hat{i} + \hat{j} + \hat{k} \\ \vec{B} &= \hat{i}\end{aligned} \right\} \theta = ?$$

$$\cos \theta = \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} = \frac{1}{\sqrt{1^2+1^2+1^2} \sqrt{1^2}} = \frac{1}{\sqrt{3}}$$

$$\cos \theta = \frac{1}{\sqrt{3}}$$

4. 2

$$\vec{A} = 3\hat{i} - 2\hat{j} + \hat{k}, \vec{B} = 12\hat{i} + 3\hat{j} - 4\hat{k}$$

$$\text{Magnitude of } \vec{A} = |\vec{A}| \cos \theta = \frac{|\vec{A}| \vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|}$$

$$= \frac{36 - 6 - 4}{\sqrt{12^2 + 3^2 + 4^2}} = \frac{26}{\sqrt{169}} = \frac{26}{13} = 2$$

Inchapter Exercise

- \hat{k} or $-\hat{k}$
 $\vec{A} = 2\hat{i} + \hat{j}$, $\vec{B} = \hat{i} + 2\hat{j}$
If $\vec{c} = \vec{A} \times \vec{B}$
 $\Rightarrow \vec{c}$ is \perp^r to both \vec{A} and \vec{B}
Hence unit vector
 \perp^r to both = \hat{c}
 \vec{A} and \vec{B}
Solve for \vec{c} and find \hat{c}
- (A)
Torque ($\vec{\tau}$) = $\vec{r} \times \vec{F}$
 $\vec{r} = 7\hat{i} + 3\hat{j} + \hat{k}$, $F = -3\hat{i} + \hat{j} + 5\hat{k}$
Solve for $\vec{\tau} = \vec{r} \times \vec{F}$
- $\theta = 60^\circ$
Given, $|\vec{A} \times \vec{B}| = \sqrt{3} \vec{A} \cdot \vec{B}$
 $|\vec{A}| |\vec{B}| \sin \theta = \sqrt{3} |\vec{A}| |\vec{B}| \cos \theta$
 $\Rightarrow \tan \theta = \sqrt{3}$ or $\theta = 60^\circ$
- $\sqrt{29}$ units
 $\vec{v} = \vec{w} \times \vec{r}$
 $\vec{w} = \hat{i} - 2\hat{j} + 2\hat{k}$
 $\vec{r} = 4\hat{j} - 3\hat{k} = 0\hat{i} + 4\hat{j} - 3\hat{k}$
Solve for $\vec{v} = \vec{w} \times \vec{r}$
Then find $|\vec{v}|$

JEE Main Exercise

- (D)
As the multiple of \hat{j} in the given vector is zero therefore this vector lies in xz plane and projection of this vector on y -axis is zero.
- (B)
If a point has coordinate (x, y, z) then its position vector = $x\hat{i} + y\hat{j} + z\hat{k}$.
- (B)
- (D)

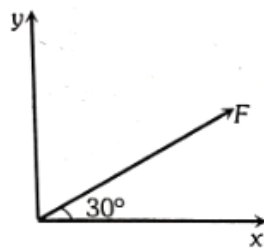
5. (C)

The X component of force F is

$$F_x = F \cos 30^\circ = F \times \frac{\sqrt{3}}{2} = \frac{\sqrt{3}}{2} F$$

The Y component of force F is

$$F_y = F \sin 30^\circ = F \times \frac{1}{2} = \frac{1}{2} F.$$



6. (A)

Resultant of vectors \vec{A} and \vec{B}

$$\vec{R} = \vec{A} + \vec{B} = 4\hat{i} + 3\hat{j} + 3\hat{k} - \hat{i} + 3\hat{j} - 8\hat{k}$$

$$\vec{R} = 3\hat{i} + 6\hat{j} - 2\hat{k}$$

$$\hat{R} = \frac{\vec{R}}{|\vec{R}|} = \frac{3\hat{i} + 6\hat{j} - 2\hat{k}}{\sqrt{3^2 + 6^2 + (-2)^2}} = \frac{3\hat{i} + 6\hat{j} - 2\hat{k}}{7}$$

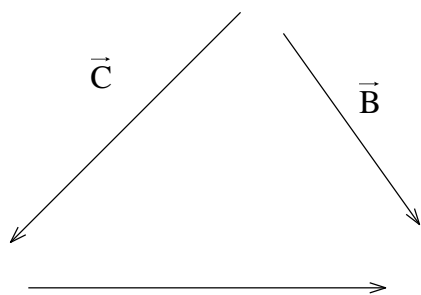
7. (D)

Unit vector in direction of $\vec{A} = \hat{A} = \frac{\vec{A}}{|\vec{A}|}$

$$\vec{A} = 5\hat{i} - 12\hat{j}$$

$$\Rightarrow \hat{A} = \frac{5\hat{i} - 12\hat{j}}{\sqrt{5^2 + (-12)^2}} = \frac{5\hat{i} - 12\hat{j}}{13}$$

8. (C)



Using Δ law $\vec{C} + \vec{A} = \vec{B}$

9. (C)

Given $0.2\hat{i} + 0.6\hat{j} + a\hat{k}$ is unit vector

$$\text{Let } \vec{p} = 0.2\hat{i} + 0.6\hat{j} + a\hat{k}$$

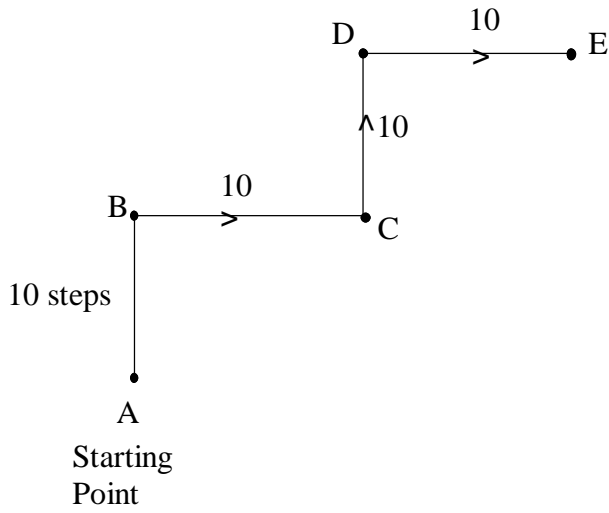
$$\Rightarrow |\vec{p}| = 1 = \sqrt{(0.2)^2 + (0.6)^2 + (a)^2}$$

On squaring both sides

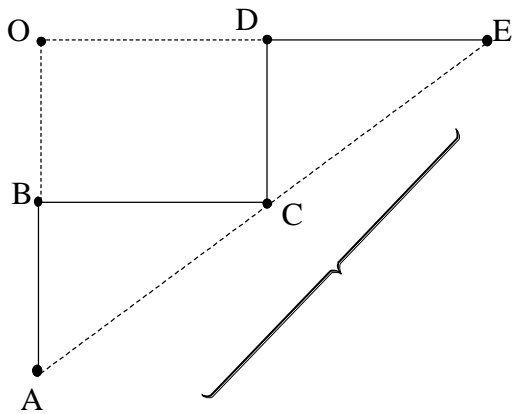
$$1^2 = 0.04 + 0.36 + a^2$$

$$1 - 0.4 = a^2 \text{ or } a = \sqrt{0.6}$$

10. (D)



(at C it u turn left. For max displacement as he should move away)
20 steps



$$AE^2 = AO^2 + OE^2$$

$$AE^2 = (20)^2 + (20)^2$$

$$AE = \sqrt{800} = 20\sqrt{2} \quad (\text{Each step is } 80 \text{ cm or } 0.8 \text{ m long})$$

$$\Rightarrow AE = 20\sqrt{2} \times 0.8 = 16\sqrt{2}$$

11. (B)

Angle between \vec{A} and \vec{B} is acute

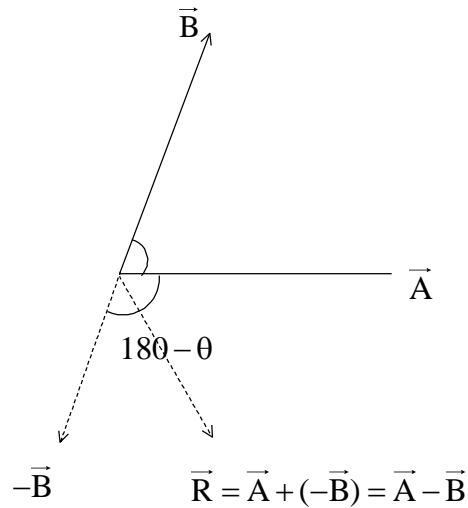
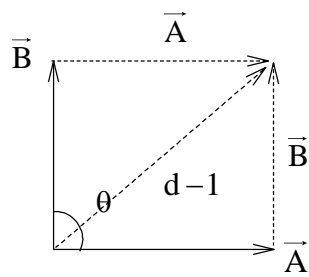
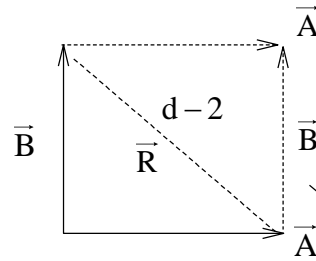


Fig - 1

Fig - 2



diagonal 1(d-1) = $\vec{A} + \vec{B}$
 \uparrow
 Major diagonal



Diagonal - 2 (d-2)
 \downarrow
 \vec{R}
 $\vec{B} + \vec{R} = \vec{A}$
 $\Rightarrow \vec{R} = \vec{A} - \vec{B}$
 \uparrow
 Minor diagonal

12. (D)

Let $\vec{R} = \vec{P} + \vec{Q}$

$\Rightarrow |\vec{P} - \vec{Q}| \leq |\vec{R}| \leq |\vec{P} + \vec{Q}|$
 $\uparrow \quad \downarrow \quad \uparrow$

When $\theta = 180^\circ$ When $\theta = 0^\circ$

R can lie anywhere between 0° and 180° both inclusive

13. (D)

When a vector is moved parallel to itself it remains same

14. (A)

$\underbrace{(\vec{A} + \vec{B}) + (\vec{A} - \vec{B})}_{= 2\vec{A}}$

As they are talking about resultant

$\Rightarrow |(\vec{A} + \vec{B}) + (\vec{A} - \vec{B})| = |2\vec{A}| = 2A$

15. (A)

For 17 N both the vector should be parallel i.e. angle between them should be zero.

For 7 N both the vectors should be antiparallel i.e. angle between them should be 180° .

For 13 N both the vectors should be perpendicular to each other i.e. angle between them should be 90° .

16. (D)

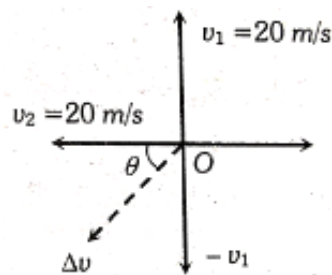
From figure

$\vec{v}_1 = 20\hat{j}$ and $\vec{v}_2 = -20\hat{j}$

$\Delta\vec{v} = \vec{v}_2 - \vec{v}_1 = -20(\hat{i} + \hat{j})$

$|\Delta\vec{v}| = 20\sqrt{2}$ and direction

$\theta = \tan^{-1}(1) = 45^\circ$ i.e. S-W



17. (C)

According to problem there should be $\sum F_x = 0$

In the given figure net force along x -axis

$$\vec{F} = 1 \cos 60^\circ \hat{i} + 2 \sin 30^\circ \hat{j} - 4 \sin 30^\circ \hat{i} = \frac{1}{2} \hat{i} + 1 \hat{j} - 2 \hat{i}$$

$$\Rightarrow \vec{F} = -\frac{1}{2} \hat{i} = -0.5 \hat{i}$$

To cancel this force minimum additional force needed is 0.5 N along the positive direction of x -axis.

18. (A)

$$\vec{P}_1 = mv \sin \theta \hat{i} - mv \cos \theta \hat{j} \text{ and } \vec{P}_2 = mv \sin \theta \hat{i} + mv \cos \theta \hat{j}$$

So, change in momentum

$$\Delta \vec{P} = \vec{P}_2 - \vec{P}_1 = 2mv \cos \theta \hat{j}, |\Delta \vec{P}| = 2mv \cos \theta.$$

19. (C)

$$R_{\max} = A + B \text{ when } \theta = 0^\circ$$

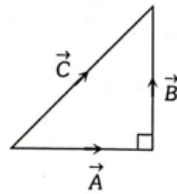
$$\therefore R_{\max} = 12 + 8 = 20 \text{ N.}$$

20. (A)

$$C = \sqrt{A^2 + B^2}$$

$$= \sqrt{3^2 + 4^2} = 5$$

\therefore Angle between \vec{A} and \vec{B} is $\frac{\pi}{2}$.



21. (A)

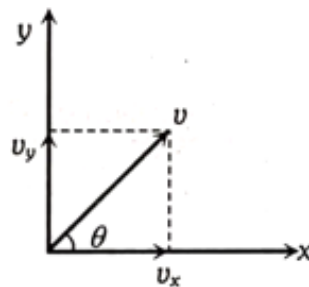
$$v_y = 20 \text{ and } v_x = 10$$

$$\therefore \text{Velocity } \vec{v} = 10 \hat{i} + 20 \hat{j}$$

Direction of velocity with x axis

$$\tan \theta = \frac{v_y}{v_x} = \frac{20}{10} = 2$$

$$\therefore \theta = \tan^{-1}(2).$$



22. (D)

$$R_{\max} = A + B = 17 \text{ when } \theta = 0^\circ$$

$$R_{\min} = A - B = 7 \text{ when } \theta = 180^\circ$$

By solving we get $A = 12$ and $B = 5$

$$\text{Now when } \theta = 90^\circ \text{ then } R = \sqrt{A^2 + B^2}$$

$$\Rightarrow R = \sqrt{(12)^2 + (5)^2} = \sqrt{169} = 13.$$

23. (C)

$$\vec{R} = \vec{S}_1 + \vec{S}_2 + \vec{S}_3$$

$$\Rightarrow R = \sqrt{12^2 + 5^2 + 6^2} = \sqrt{144 + 25 + 36} = \sqrt{205} = 14.31 \text{ m}$$

24. (D)

$A = 3 \text{ N}, B = 2\text{N}$ then $R = \sqrt{A^2 + B^2 + 2AB \cos \theta}$

$$R = \sqrt{9 + 4 + 12 \cos \theta} \quad \dots\text{(i)}$$

Now $A = 6\text{N}, B = 2\text{N}$ then

$$2R = \sqrt{36 + 4 + 24 \cos \theta} \quad \dots\text{(ii)}$$

From (i) and (ii) we get $\cos = -\frac{1}{2}$

$\therefore \theta = 120^\circ$.

25. (A)

$$a = \frac{|\vec{v}_f - \vec{v}_i|}{t} = \frac{\sqrt{30^2 + 40^2}}{10} = 5 \text{ m/s}^2$$

26. (A)

$$\vec{R} = 2\hat{i} + 5\hat{j} + 3\hat{k}$$

27. (D)

If $|\vec{F}_1| = F_1 = 4, |\vec{F}_2| = F_2 = 3$

And $\vec{F}_R = \vec{F}_1 + \vec{F}_2$

$$\Rightarrow 1 = |F_1 - F_2| \leq |\vec{F}_R| \leq F_1 + F_2 = 7$$

28. (B)

$|\vec{F}_1| = 6, |\vec{F}_2| = 8$

$$\vec{F}_R = \vec{F}_1 + \vec{F}_2$$

$$\Rightarrow |F_1 - F_2| = 2 \leq |\vec{F}_R| \leq F_1 + F_2 = 6 + 8 = 17$$

↓

Hence only possible option is B ie 11 N

29. (C)

$$\vec{F}_1 + \vec{F}_2 + \vec{F}_3 = 0$$

↑

For this always add two smaller forces.

The result of above is then added to 3rd force and then check if it can give zero

Ans. (C)

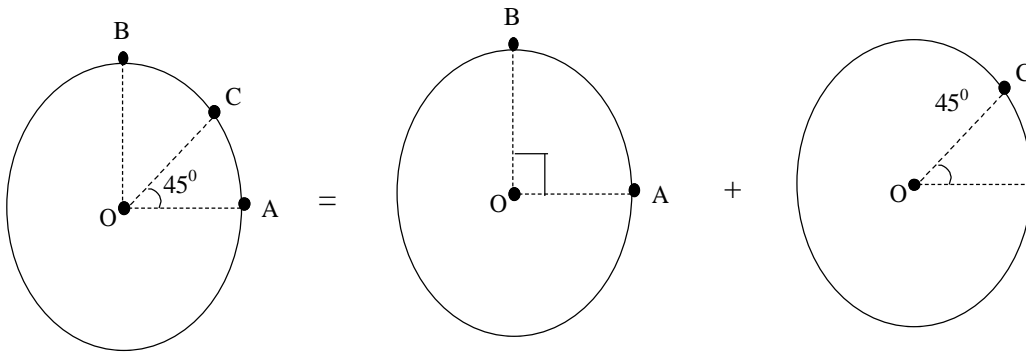
(1, 2, 1) $\Rightarrow 1+1 = 2$ (Two smaller forces)

New $2 + 2 = 4$ and $2 - 2 = 0$

↑

3rd force

30. (D)



Let $\vec{P} = \vec{OA} + \vec{OB}$

$$|\vec{P}| = \sqrt{R^2 + R^2 + 2(R)(R) \cos 90}$$

$$|\vec{P}| = R\sqrt{2}$$

Angle between \vec{A} and $\vec{P} \Rightarrow \tan \alpha = \frac{B \sin \theta}{A + B \cos \theta}$

$$\tan \alpha = \frac{R \sin 90}{R + R \cos 90} = \frac{R}{R} = 1 \Rightarrow \alpha = 45^\circ$$

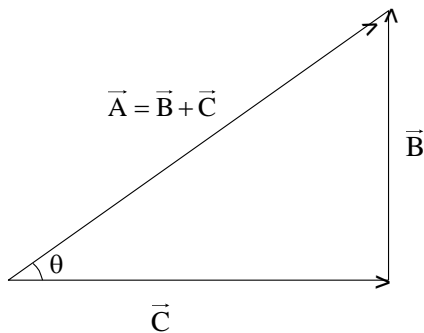
c) \vec{P} and \vec{OC} both are along same direction ie angle between them = 0°

$$\Rightarrow |\vec{P} + \vec{OC}| = R\sqrt{2} + R = R(\sqrt{2} + 1)$$

31. (A)

$$\vec{A} = \vec{B} + \vec{C}, |\vec{A}| = 5, |\vec{B}| = 4, |\vec{C}| = 3$$

Pythagoras Triplets



$$\cos \theta = \frac{|\vec{C}|}{|\vec{A}|} = \frac{3}{5} \Rightarrow \theta = \cos^{-1}\left(\frac{3}{5}\right)$$

32. (D)

$$\vec{A} + \vec{B} = \vec{A} - \vec{B}$$

$$\Rightarrow \vec{A} + \vec{B} - \vec{A} + \vec{B} = 0$$

$$2\vec{B} = 0 \text{ or } \vec{B} = 0$$

33. (B)

$$|\vec{F}_1| = F, |\vec{F}_2| = F$$

Let $\vec{F}_R = \vec{F}_1 + \vec{F}_2$ then $|\vec{F}_R| = F$

Given $|\vec{F}_R| = \sqrt{F_1^2 + F_2^2 + 2F_1F_2 \cos \theta}$

$$F = \sqrt{F^2 + F^2 + 2(F)(F) \cos \theta}$$

On squaring

$$F^2 = 2F^2 + 2F^2 \cos \theta = 2F^2(1 + \cos \theta)$$

$$\Rightarrow \frac{F^2}{2F^2} = 1 + \cos \theta \text{ or } 1 + \cos \theta = \frac{1}{2}$$

$$\Rightarrow \cos \theta = \frac{1}{2} - 1 = \frac{-1}{2}$$

$$\Rightarrow \theta = 120^\circ \text{ or } 240^\circ$$

Ans θ is smaller of the two

34. (B)

$$\vec{A} = 2\hat{i} - \hat{j} + \hat{k}, \vec{B} = \hat{i} - 3\hat{j} - 5\hat{k}$$

$$\vec{C} = 3\hat{i} - 4\hat{j} - 4\hat{k} \text{ Find } |\vec{A}|, |\vec{B}| \text{ and } |\vec{C}| \text{ then use properties of } \Delta$$

Ans.: For equilateral $\Delta \Rightarrow |\vec{A}| = |\vec{B}| = |\vec{C}|$

In our case $|\vec{A}|^2 + |\vec{B}|^2 = |\vec{C}|^2$ Rt Δ

35. (B)

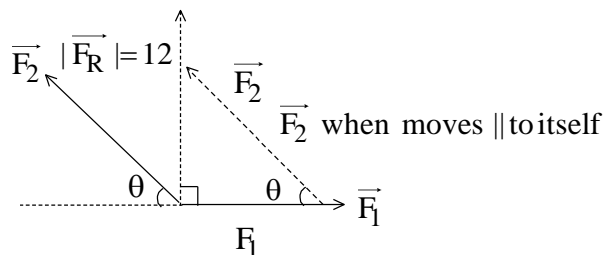
$$|\vec{F}_1| = F_1, |\vec{F}_2| = F_2 \quad (\text{Let } F_1 < F_2)$$

$$\text{Let } \vec{F}_R = \vec{F}_1 + \vec{F}_2$$

$$\text{Given } -F_1 + F_2 = 18, |\vec{F}_R| = 12$$

$$\text{And } \vec{F}_R \perp^r \vec{F}_1$$

$$\vec{F}_2$$



$$\text{From rt}\Delta, \tan \theta = \frac{F_R = 12}{F_1} \Rightarrow F_1 = \frac{12}{\tan \theta} = 2 \cot \theta$$

$$\sin \theta = \frac{F_R = 12}{F_2} \Rightarrow F_2 = \frac{12}{\sin \theta} = 12 \operatorname{cosec} \theta$$

$$\text{As } F_1 + F_2 = 18$$

↓

$$12 \cot \theta + 12 \operatorname{cosec} \theta = 18$$

$$12 \left[\frac{\cos \theta}{\sin \theta} + \frac{1}{\sin \theta} \right] = 18$$

$$\Rightarrow \frac{\cos \theta + 1}{\sin \theta} = \frac{3}{2}$$

$$\Rightarrow 2 \cos \theta + 12 = 3 \sin \theta$$

$$2 \cos \theta + 2 = 3 \left(\sqrt{1 - \cos^2 \theta} \right)$$

Squaring both sides $(\because \sin^2 \theta + \cos^2 \theta = 1)$

$$(2 \cos \theta + 2)^2 = \left(3\sqrt{1 - \cos^2 \theta}\right)^2$$

$$4 \cos^2 \theta + 4 + 8 \cos \theta = 9(1 - \cos^2 \theta)$$

$$4 \cos^2 \theta + 4 + 8 \cos \theta - 9 + 9 \cos^2 \theta = 0$$

$$13 \cos^2 \theta + 8 \cos \theta - 5 = 0$$

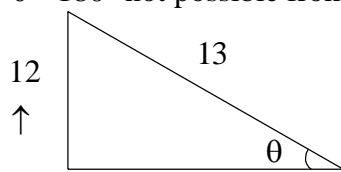
$$13 \cos^2 \theta + 13 \cos \theta - 5 \cos \theta - 5 = 0$$

$$13 \cos \theta [\cos \theta + 1] - 5(\cos \theta + 1) = 0$$

$$\Rightarrow (\cos \theta + 1)(13 \cos \theta - 5) = 0$$

$$\Rightarrow \cos \theta = -1 \text{ or } \cos \theta = \frac{5}{13}$$

$\theta = 180^\circ$ not possible from figure $\theta = \text{acute}$



5 (Pythagoras theorem)

\Rightarrow from fig.

$$\sin \theta = \frac{12}{13}$$

$$\cos \theta = \frac{5}{13}$$

$$\text{As } F_1 = 12 \cot \theta = 12 \times \frac{\cos \theta}{\sin \theta} = 12 \times \frac{5/13}{12/13}$$

$$\Rightarrow F_1 = 5$$

$$\text{As } F_2 = 12 \operatorname{cosec} \theta = \frac{12}{\sin \theta} = \frac{12}{12/13} = 13$$

36. (C)

$$\vec{A} = 2\hat{i} + 3\hat{j}, \vec{B} = \hat{i} + \hat{j}$$

Component of \vec{A} along $\vec{B} = |\hat{A}| \cos \theta \hat{B}$

$$= |\vec{A}| \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} \hat{B}$$

$$= \frac{\vec{A} \cdot \vec{B}}{|\vec{B}|} \hat{B}$$

$$= \left[\frac{(2\hat{i} + 3\hat{j}) \cdot (\hat{i} + \hat{j})}{\sqrt{1^2 + 1^2}} \right] \frac{(\hat{i} + \hat{j})}{\sqrt{1^2 + 1^2}}$$

$$= \frac{(2+3)}{\sqrt{2}} \frac{(\hat{i} + \hat{j})}{\sqrt{2}}$$

$$\text{Ans.} = \frac{5}{2} \hat{i} + \hat{j}$$

37. (C)

Given vectors can be rewritten as $\vec{A} = 2\hat{i} + 3\hat{j} + 8\hat{k}$ and $\vec{B} = -4\hat{i} + 4\hat{j} + \alpha\hat{k}$

Dot product of these vectors should be equal to zero because they are perpendicular.

$$\therefore \vec{A} \cdot \vec{B} = -8 + 12 + 8\alpha = 0 \Rightarrow 8\alpha = -4 \Rightarrow \alpha = -\frac{1}{2}.$$

38. (A)

$$\vec{A} = \hat{i} + \hat{j} + \hat{k}; \quad \vec{B} = \hat{i} + \hat{j}$$

$$\therefore A = \sqrt{1^2 + 1^2 + 1^2} = \sqrt{3}, \quad B = \sqrt{1^2 + 1^2} = \sqrt{2}$$

$$\vec{A} \cdot \vec{B} = 2$$

$$\cos \theta = \frac{\vec{A} \cdot \vec{B}}{AB} = \frac{2}{\sqrt{3}\sqrt{2}} = \left(\frac{\sqrt{2}}{\sqrt{3}} \right)$$

$$\sin \theta = \sqrt{1 - \cos^2 \theta} = \sqrt{1 - \frac{2}{3}} = \sqrt{\frac{1}{3}} = \frac{1}{\sqrt{3}}$$

$$\therefore \theta = \sin^{-1} \left(\frac{1}{\sqrt{3}} \right).$$

39. (A)

$$S = \vec{r}_2 - \vec{r}_1$$

$$\begin{aligned} W &= \vec{F} \cdot \vec{S} = (4\hat{i} + \hat{j} + 3\hat{k}) \cdot (11\hat{i} + 11\hat{j} + 15\hat{k}) \\ &= (4 \times 11 + 1 \times 11 + 3 \times 15) = 100 \text{ J.} \end{aligned}$$

40. (B)

$$\text{Let } \vec{A} \cdot (\vec{B} \times \vec{A}) = \vec{A} \cdot \vec{C}$$

Here $\vec{C} = \vec{B} \times \vec{A}$ which is perpendicular to both vector \vec{A} and \vec{B}

$$\therefore \vec{A} \cdot \vec{C} = 0.$$

41. (A)

$$\vec{L} = \vec{r} \times \vec{p} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 2 & -1 \\ 3 & 4 & -2 \end{vmatrix} = -\hat{j} - 2\hat{k}$$

i.e. the angular momentum is perpendicular to x -axis.

42. (C)

$$\vec{A} \cdot \vec{B} = 0 \quad \therefore \theta = 90^\circ.$$

43. (D)

$$\vec{P} = 2\hat{i} + b\hat{j} + 2\hat{k}$$

$$\vec{Q} = \hat{i} + \hat{j} + \hat{k}$$

Given \vec{P} is \perp^r to \vec{Q}

$$\Rightarrow \vec{P} \cdot \vec{Q} = |\vec{P}| |\vec{Q}| \cos 90 = 0$$

$$2 + b + 2 = 0 \Rightarrow b = -4$$

44. (D)

\vec{A} , \vec{B} and \vec{C} are three vectors

Concept – Vector or Dot product can be performed only between two vectors

45. (D)

Given $|\vec{A}| = |\vec{B}|$ and \vec{A} is \perp^r to \vec{B}

To find which of the following is \perp^r to $\vec{A} + \vec{B}$

(A) $\vec{A} \times \vec{B} \leftarrow \because$ it will give a vector \perp^r to both \vec{A} and \vec{B} i.e. \perp^r to plane of \vec{A} and \vec{B} .

(B) $\vec{A} - \vec{B} \leftarrow$ To check perform Dot product of $(\vec{A} + \vec{B}) \cdot (\vec{A} - \vec{B})$ if it is = 0 then yes.

(C) $3\vec{A} - 3\vec{B} \leftarrow$ Same as B option

(D) all of these

46. (D)

$$\vec{A} \cdot (\vec{B} \times \vec{A}) = 0$$

$\vec{A} \cdot$ gives vector \perp^r to \vec{A} and \vec{B}

Dot Product = 0 ($\because \theta = 90^\circ$ and $\cos 90 = 0$)

47. (A)

$$\text{Given } \vec{A} \times \vec{B} = \vec{B} \times \vec{A}$$

$$\text{We know } \vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$

$$\text{Hence } -\vec{B} \times \vec{A} = \vec{B} \times \vec{A}$$

$$\text{Or } 0 = \vec{B} \times \vec{A} + \vec{B} \times \vec{A} \text{ or } 2\vec{B} \times \vec{A} = 0$$

$$\Rightarrow \vec{B} \times \vec{A} = 0 \Rightarrow \theta = 0^\circ \text{ or } \pi$$

$$\because \vec{A} \neq 0, \vec{B} \neq 0$$

48. (B)

$$\vec{A} \cdot \vec{B} = |\vec{A} \times \vec{B}| \text{ given}$$

$$|\vec{A}| |\vec{B}| \cos \theta = |\vec{A}| |\vec{B}| \sin \theta$$

$$\Rightarrow \cos \theta = \sin \theta \Rightarrow \theta = 45^\circ$$

49. (A)

$$\text{Let } \vec{A} = \hat{i}, \vec{B} = \hat{i} + \hat{j} + \hat{k}$$

$$\text{Hence } \cos \theta = \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} = \frac{(\hat{i}) \cdot (\hat{i} + \hat{j} + \hat{k})}{\sqrt{1^2} \sqrt{1^2 + 1^2 + 1^2}}$$

$$\cos \theta = \frac{1}{\sqrt{1} \sqrt{3}} = \frac{1}{\sqrt{3}}$$

$$\theta = \cos^{-1} \left(\frac{1}{\sqrt{3}} \right)$$

1. (c)

$$\text{Given } |\vec{A} + \vec{B}| = |\vec{A} - \vec{B}| \times 2$$

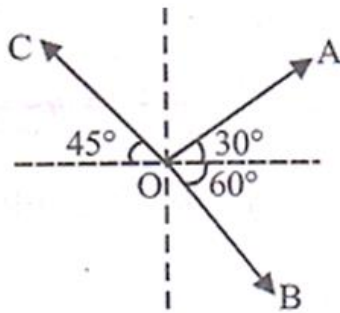
$$\Rightarrow |\vec{A} + \vec{B}|^2 = |\vec{A} - \vec{B}|^2 \times 4$$

$$\Rightarrow 0 = 3|A|^2 + 3|B|^2 - |10|A||B|\cos\theta$$

$$\Rightarrow 0 - 3|A|^2 + 3|A|^2 - |10|A|^2 \cos\theta \Rightarrow |10|A|^2 \cos\theta = 6|A|^2$$

$$\Rightarrow \cos\theta = \frac{3}{5}$$

2. (a)



Say, magnitudes of vectors is r.

$$\vec{OA} = r [\cos 30^\circ \hat{i} + \sin 30^\circ \hat{j}] = r \left[\frac{\sqrt{3}}{2} \hat{i} + \frac{1}{2} \hat{j} \right]$$

$$\vec{OC} = r [\cos 45^\circ (-\hat{i}) + \sin 45^\circ \hat{j}] = r \left[-\frac{1}{\sqrt{2}} \hat{i} + \frac{1}{\sqrt{2}} \hat{j} \right]$$

$$\vec{OB} = r [\cos 60^\circ \hat{i} - \sin 60^\circ \hat{j}] = r \left[\frac{1}{2} \hat{i} - \frac{\sqrt{3}}{2} \hat{j} \right]$$

$$\therefore \vec{OA} + \vec{OB} - \vec{OC}$$

$$= r \left[\left(\frac{\sqrt{3}+1}{2} + \frac{1}{\sqrt{2}} \right) \hat{i} + \left(\frac{1}{2} - \frac{\sqrt{3}}{2} - \frac{1}{\sqrt{2}} \right) \hat{j} \right]$$

\therefore Angle made by vector with x-axis

$$\tan^{-1} \left[\frac{\frac{1}{2} - \frac{\sqrt{3}}{2} - \frac{1}{\sqrt{2}}}{\frac{\sqrt{3}+1}{2} + \frac{1}{\sqrt{2}}} \right] = \tan^{-1} \left[\frac{1 - \sqrt{3} - \sqrt{2}}{\sqrt{3} + 1 + \sqrt{2}} \right]$$

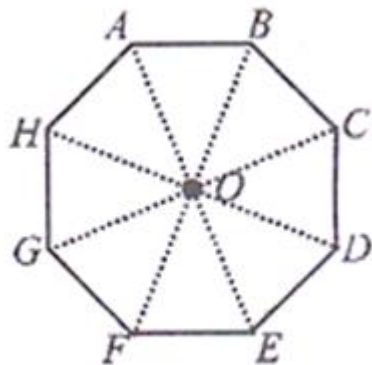
3. (d)

Projection of vector \vec{A} on vector \vec{B} is given by

$$(A \cos \theta) \hat{B} = A \left(\frac{\vec{A} \cdot \vec{B}}{AB} \right) \hat{B} = \frac{\vec{A} \cdot \vec{B}}{B} \hat{B}$$

$$= \frac{2}{\sqrt{2}} \left(\frac{\hat{i} + \hat{j}}{\sqrt{2}} \right) = \hat{i} + \hat{j}$$

4. (c)



From figure,

$$\overline{AO} + \overline{OB} = \overline{AB} \quad \overline{AO} + \overline{OC} = \overline{AC} \quad \overline{AO} + \overline{OD} = \overline{AD}$$

$$\overline{AO} + \overline{OE} = \overline{AE} \quad \overline{AO} + \overline{OF} = \overline{AF} \quad \overline{AO} + \overline{OG} = \overline{AG}$$

$$\overline{AO} + \overline{OH} = \overline{AH}$$

Now, adding we get

$$8\overline{AO} = (\overline{AB} + \overline{AC} + \overline{AD} + \overline{AE} + \overline{AF} + \overline{AG} + \overline{AH})$$

$$\Rightarrow 8(2\hat{i} + 3\hat{j} - 4\hat{k}) = \overline{AB} + \overline{AC} + \overline{AD} + \overline{AE} + \overline{AF} + \overline{AG} + \overline{AH}$$

$$\therefore \overline{AB} + \overline{AC} + \overline{AD} + \overline{AE} + \overline{AF} + \overline{AG} + \overline{AH}$$

$$= 16\hat{i} + 24\hat{j} - 32\hat{k}$$

5. (d)

Using

$$R^2 = A_1^2 + A_2^2 + 2A_1A_2 \cos \theta$$

$$5^2 = 3^2 + 5^2 + 2 \times 3 \times 5 \cos \theta \text{ or } \cos \theta = -0.3$$

$$(2\vec{A}_1 + 3\vec{A}_2) \cdot (3\vec{A}_1 - 2\vec{A}_2) = 2A_1 \times 3A_1 + (3A_2)(3A_1) \cos \theta - (2A_1)(2A_2) \cos \theta - 3A_2 \times 2A_2$$

$$= 6A_1^2 + 9A_1A_2 \cos \theta - 4A_1A_2 \cos \theta - 6A_2^2$$

$$= 6A_1^2 - 6A_2^2 + 5A_1A_2 \cos \theta$$

$$= 6 \times 3^2 - 6 \times 5^2 + 5 \times 3 \times 5 (-0.3) = -118.5$$

6. (c)

From figure, $\vec{r}_G = \frac{a}{2}\hat{i} + \frac{a}{2}\hat{k}$

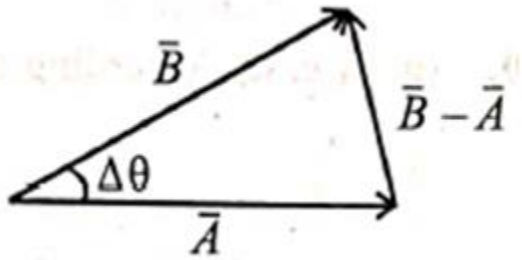
$$\vec{r}_H = \frac{a}{2}\hat{j} + \frac{a}{2}\hat{k}$$

$$\therefore \vec{r}_H - \vec{r}_G = \left(\frac{a}{2}\hat{j} + \frac{a}{2}\hat{k} \right) - \left(\frac{a}{2}\hat{i} + \frac{a}{2}\hat{k} \right) = \frac{a}{2}(\hat{j} - \hat{i})$$

7. (a)

Arc length = radius \times angle

So, $|\vec{B} - \vec{A}| = |\vec{A}| \Delta\theta$



$|\vec{A}| = |\vec{B}|$

8.

(a)

If $\vec{C} = a\hat{i} + b\hat{j}$ then $\vec{A} \cdot \vec{C} = \vec{A} \cdot \vec{B}$

$a + b = 1$ (i)

$\vec{B} \cdot \vec{C} = \vec{A} \cdot \vec{B}$

$2a - b = 1$ (ii)

Solving equation (i) and (ii) we get

$a = \frac{1}{3}, b = \frac{2}{3}$

\therefore Magnitude of coplanar vector, $|\vec{C}| = \sqrt{\frac{1}{9} + \frac{4}{9}} = \sqrt{\frac{5}{9}}$

9.

(a)

Here $\vec{P} + b\vec{R} = \vec{S} \Rightarrow \vec{R} = \frac{\vec{S} - \vec{P}}{b}$

Also $\vec{R} = \vec{Q} - \vec{P}$

$\therefore \frac{\vec{S} - \vec{P}}{b} = \vec{Q} - \vec{P} \Rightarrow \vec{S} - \vec{P} = b\vec{Q} - b\vec{P}$

$\therefore \vec{S} = b\vec{Q} + (1 - b)\vec{P}$

10.

(5)

Here, $\vec{a} \cdot \vec{b} = 0$

$\therefore \vec{a} \cdot \vec{b} = (2\hat{i} + 4\hat{j} - 2\hat{k}) \cdot (\hat{i} + 2\hat{j} + \alpha\hat{k}) = 0$

$\therefore 2 \times 1 + 4 \times 2 - 2 \times \alpha = 0 \therefore \alpha = 5$

11.

(2)

Given that

$\vec{A} = (2\hat{i} + 3\hat{j} - \hat{k})m$ and $\vec{B} = (\hat{i} + 2\hat{j} + 2\hat{k})m$

Component of vector \vec{A} along vector $\vec{B} = \frac{\vec{A} \cdot \vec{B}}{|\vec{B}|}$

$= \frac{\vec{A} \cdot \vec{B}}{|\vec{B}|} = \frac{2 + 6 - 2}{\sqrt{1^2 + 2^2 + 2^2}} \left(\because \hat{B} = \frac{\vec{B}}{|\vec{B}|} \right)$

$= \frac{6}{3} = 2m$

12. (3)

Direction of particle P,

$$\hat{v}_1 = \pm \frac{\vec{A} \times \vec{B}}{|\vec{A} \times \vec{B}|} = \pm \frac{\hat{i} - \hat{j} + \hat{k}}{\sqrt{3}}$$

Direction of particle Q,

$$\hat{v}_2 = \pm \frac{\vec{A} \times \vec{C}}{|\vec{A} \times \vec{C}|} = \pm \frac{2\hat{k}}{2} = \pm \hat{k}$$

Angle between \hat{v}_1 and \hat{v}_2

$$\frac{\hat{v}_1 \cdot \hat{v}_2}{|\hat{v}_1| |\hat{v}_2|} = \frac{\pm 1}{(1)(1)} = \pm \frac{1}{\sqrt{3}}$$

Hence the angle between the direction of motion of P and Q is $\cos^{-1}\left(\frac{1}{\sqrt{3}}\right)$

\therefore value of $x = 3$

13. (180)

$\vec{P} \times \vec{Q} = \vec{Q} \times \vec{P}$ only if $\vec{P} = 0$ or $\vec{Q} = 0$

$$\Rightarrow \vec{P} \times \vec{Q} = 0$$

So, $\theta = 0^\circ$ or 180° and $0^\circ < \theta < 360^\circ$.

$\therefore \theta = 180^\circ$

14. (195)

Given: $\vec{F} = (\hat{i} + 2\hat{j} + 3\hat{k})\text{N}$

And, $\vec{r} = [(4\hat{i} + 3\hat{j} - \hat{k}) - (\hat{i} + 2\hat{j} + \hat{k})] = 3\hat{i} + \hat{j} - 2\hat{k}$

Torque, $\tau = \vec{r} \times \vec{F} = (3\hat{i} + \hat{j} - 2\hat{k}) \times (\hat{i} + 2\hat{j} + 3\hat{k})$

$$\tau = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 3 & 1 & -2 \\ 1 & 2 & 3 \end{vmatrix} = 7\hat{i} - 11\hat{j} + 5\hat{k}$$

Magnitude of torque, $|\tau| = \sqrt{195}$

15. (90)

Given,

$$|\vec{R}| = |\vec{P}| \Rightarrow |\vec{P} + \vec{Q}| = |\vec{P}|$$

$$P^2 + Q^2 + 2PQ \cos \theta = P^2$$

$$\Rightarrow Q + 2P \cos \theta = 0$$

$$\Rightarrow \cos \theta = -\frac{Q}{2P} \quad \dots(i)$$

$$\tan \alpha = \frac{2P \sin \theta}{Q + 2P \cos \theta} = \infty (\because 2P \cos \theta + Q = 0)$$

$$\Rightarrow \alpha = 90^\circ$$

