

Inchapter Exercise

1. $\theta = 45^\circ$

Let two forces be \vec{F}_1 and \vec{F}_2 , $|\vec{F}_1| = F_1 = 2F$, $|\vec{F}_2| = F_2 = F\sqrt{2}$

Let angle between them be $\theta = ?$

Let $\vec{F}_R = \vec{F}_1 + \vec{F}_2$

$$\Rightarrow |\vec{F}_R| = \sqrt{F_1^2 + F_2^2 + 2F_1F_2 \cos \theta}$$

$$\text{Given } F_R = F\sqrt{10} = \sqrt{(2F)^2 + (F\sqrt{2})^2 + 2(2F)(F\sqrt{2})\cos \theta}$$

$$F\sqrt{10} = \sqrt{4F^2 + 2F^2 + 4F^2\sqrt{2}\cos \theta}$$

Squaring both sides

$$(F\sqrt{10})^2 = 4F^2 + 2F^2 + 4F^2\sqrt{2}\cos \theta$$

$$\Rightarrow 10F^2 = 6F^2 + 4F^2\sqrt{2}\cos \theta$$

$$\Rightarrow \cos \theta = \frac{1}{\sqrt{2}} \Rightarrow \theta = 45^\circ$$

2. **30 N, 40 N**

Let force be $\vec{F}_1, |\vec{F}_1| = F_1, \vec{F}_2, |\vec{F}_2| = F_2$

Let $F_1 > F_2$

Case - 1 \vec{F}_1 oppo. to \vec{F}_2

$$\text{ie if } \left. \begin{array}{l} \vec{F}_1 \rightarrow \\ \vec{F}_2 \leftarrow \end{array} \right\} \theta = 180^\circ$$

$$|\vec{F}_1 + \vec{F}_2| = \sqrt{F_1^2 + F_2^2 + 2F_1F_2 \cos 180^\circ}$$

Case 1

$$\downarrow \sqrt{F_1^2 + F_2^2 + 2F_1F_2(-1)}$$

$$10N = \sqrt{(F_1 - F_2)^2} = F_1 - F_2 \text{ (as } F_1 > F_2)$$

$$\Rightarrow F_1 - F_2 = 10N \quad \dots\dots(1)$$

Case - 2 - $\vec{F}_1 \perp^r$ to \vec{F}_2 i.e $\theta = 90^\circ$

$$\Rightarrow |\vec{F}_1 + \vec{F}_2| = \sqrt{F_1^2 + F_2^2 + 2F_1F_2 \cos 90^\circ}$$

\downarrow
 $= 0$

$$\text{So } = \sqrt{F_1^2 + F_2^2}$$

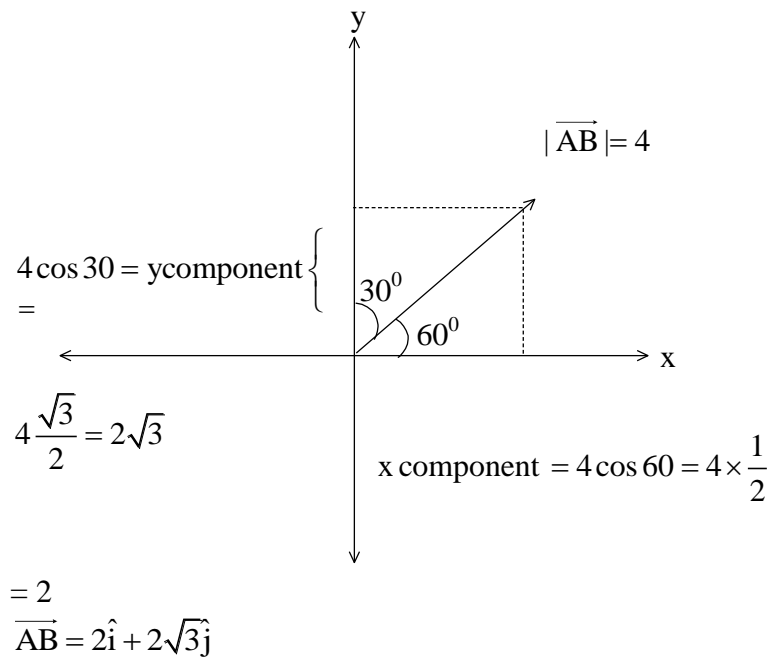
Squaring both sides

$$(50)^2 = F_1^2 + F_2^2 \text{ or } F_1^2 + F_2^2 = 2500 \quad \dots\dots(2)$$

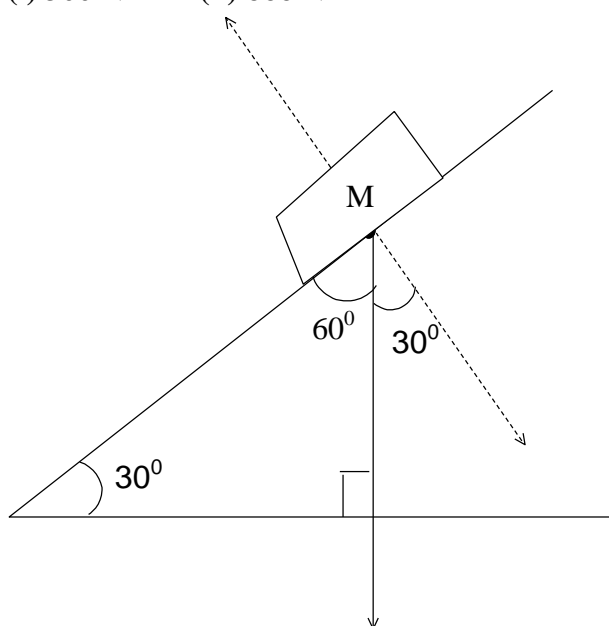
Solve equation (1) and (2) to get F_1 and F_2

Inchapter Exercise

1. $|\vec{AB}| = 4$, $\theta_x = 60^\circ$ and \vec{AB} lies in 1st quadrant.



2. (i) 500 N (ii) 866 N



$w = \text{weight} = 1000\text{N}$

Component in direction to plane $\parallel = 1000 \cos 60 = 500$

Component in direction $\perp = 1000 \cos 30 = 500\sqrt{3}$ to plane.

3. $2\vec{A} - 3\vec{B} = (4\hat{i} + 2\hat{j}) - (9\hat{j} - 3\hat{k})$

$$\vec{A} = 2\hat{i} + \hat{j}, \vec{B} = 3\hat{j} - \hat{k}$$

$$\Rightarrow 2\vec{A} = 4\hat{i} + 2\hat{j}$$

$$\Rightarrow 3\vec{B} = 9\hat{j} - 3\hat{k}$$

$$\begin{aligned} \text{Hence } 2\vec{A} - 3\vec{B} &= (4\hat{i} + 2\hat{j}) - (9\hat{j} - 3\hat{k}) \\ &= 4\hat{i} - 7\hat{j} + 3\hat{k} \end{aligned}$$

Inchapter Exercise

1. $\theta = 30^\circ$

$$\left. \begin{aligned} \vec{A} &= 2\hat{i} + \hat{j} - \hat{k} \\ \vec{B} &= \hat{i} - \hat{k} \end{aligned} \right\} \theta = ?$$

$$\begin{aligned} \cos \theta &= \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} = \frac{(2+1)}{\sqrt{2^2+1^2+1^2} \sqrt{2}} \\ &= \frac{3}{\sqrt{12}} = \frac{3}{2\sqrt{3}} = \frac{(\sqrt{3})(\sqrt{3})}{2\sqrt{3}} \end{aligned}$$

$$\cos \theta = \frac{\sqrt{3}}{2} \Rightarrow \theta = 30^\circ$$

2. $m = 3/14$

$$\left. \begin{aligned} \vec{A} &= 4\hat{i} + \hat{j} - 3\hat{k} \\ \vec{B} &= 2m\hat{i} + 6m\hat{j} + \hat{k} \end{aligned} \right\} \vec{A} \perp \vec{B} \text{ given}$$

$$\Rightarrow \vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos 90 = 0$$

$$\Rightarrow 8m + 6m - 3 = 0$$

$$\Rightarrow m = \frac{3}{14}$$

3. $\cos \theta = \frac{1}{\sqrt{3}}$

$$\left. \begin{aligned} \vec{A} &= \hat{i} + \hat{j} + \hat{k} \\ \vec{B} &= \hat{i} \end{aligned} \right\} \theta = ?$$

$$\cos \theta = \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} = \frac{1}{\sqrt{1^2+1^2+1^2} \sqrt{1^2}} = \frac{1}{\sqrt{3}}$$

$$\cos \theta = \frac{1}{\sqrt{3}}$$

4. 2

$$\vec{A} = 3\hat{i} - 2\hat{j} + \hat{k}, \vec{B} = 12\hat{i} + 3\hat{j} - 4\hat{k}$$

$$\text{Magnitude of } \vec{A} = |\vec{A}| \cos \theta = \frac{|\vec{A}| \vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|}$$

$$= \frac{36 - 6 - 4}{\sqrt{12^2 + 3^2 + 4^2}} = \frac{26}{\sqrt{169}} = \frac{26}{13} = 2$$

Inchapter Exercise

- \hat{k} or $-\hat{k}$
 $\vec{A} = 2\hat{i} + \hat{j}$, $\vec{B} = \hat{i} + 2\hat{j}$
If $\vec{c} = \vec{A} \times \vec{B}$
 $\Rightarrow \vec{c}$ is \perp^r to both \vec{A} and \vec{B}
Hence unit vector
 \perp^r to both = \hat{c}
 \vec{A} and \vec{B}
Solve for \vec{c} and find \hat{c}
- (A)
Torque ($\vec{\tau}$) = $\vec{r} \times \vec{f}$
 $\vec{r} = 7\hat{i} + 3\hat{j} + \hat{k}$, $F = -3\hat{i} + \hat{j} + 5\hat{k}$
Solve for $\vec{\tau} = \vec{r} \times \vec{F}$
- $\theta = 60^\circ$
Given, $|\vec{A} \times \vec{B}| = \sqrt{3} \vec{A} \cdot \vec{B}$
 $|\vec{A}| |\vec{B}| \sin \theta = \sqrt{3} |\vec{A}| |\vec{B}| \cos \theta$
 $\Rightarrow \tan \theta = \sqrt{3}$ or $\theta = 60^\circ$
- $\sqrt{29}$ units
 $\vec{v} = \vec{w} \times \vec{r}$
 $\vec{w} = \hat{i} - 2\hat{j} + 2\hat{k}$
 $\vec{r} = 4\hat{j} - 3\hat{k} = 0\hat{i} + 4\hat{j} - 3\hat{k}$
Solve for $\vec{v} = \vec{w} \times \vec{r}$
Then find $|\vec{v}|$

JEE Main Exercise

- (D)
As the multiple of \hat{j} in the given vector is zero therefore this vector lies in xz plane and projection of this vector on y -axis is zero.
- (B)
If a point has coordinate (x, y, z) then its position vector = $x\hat{i} + y\hat{j} + z\hat{k}$.
- (B)
- (D)

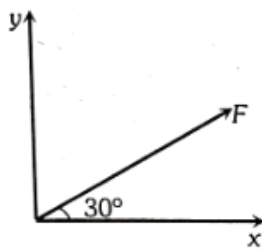
5. (C)

The X component of force F is

$$F_x = F \cos 30^\circ = F \times \frac{\sqrt{3}}{2} = \frac{\sqrt{3}}{2} F$$

The Y component of force F is

$$F_y = F \sin 30^\circ = F \times \frac{1}{2} = \frac{1}{2} F.$$



6. (A)

Resultant of vectors \vec{A} and \vec{B}

$$\vec{R} = \vec{A} + \vec{B} = 4\hat{i} + 3\hat{j} + 3\hat{k} - \hat{i} + 3\hat{j} - 8\hat{k}$$

$$\vec{R} = 3\hat{i} + 6\hat{j} - 2\hat{k}$$

$$\hat{R} = \frac{\vec{R}}{|\vec{R}|} = \frac{3\hat{i} + 6\hat{j} - 2\hat{k}}{\sqrt{3^2 + 6^2 + (-2)^2}} = \frac{3\hat{i} + 6\hat{j} - 2\hat{k}}{7}$$

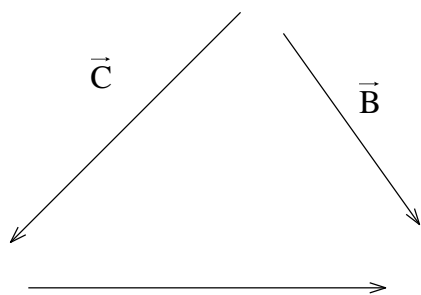
7. (D)

Unit vector in direction of $\vec{A} = \hat{A} = \frac{\vec{A}}{|\vec{A}|}$

$$\vec{A} = 5\hat{i} - 12\hat{j}$$

$$\Rightarrow \hat{A} = \frac{5\hat{i} - 12\hat{j}}{\sqrt{5^2 + (-12)^2}} = \frac{5\hat{i} - 12\hat{j}}{13}$$

8. (C)



Using Δ law $\vec{C} + \vec{A} = \vec{B}$

9. (C)

Given $0.2\hat{i} + 0.6\hat{j} + a\hat{k}$ is unit vector

$$\text{Let } \vec{p} = 0.2\hat{i} + 0.6\hat{j} + a\hat{k}$$

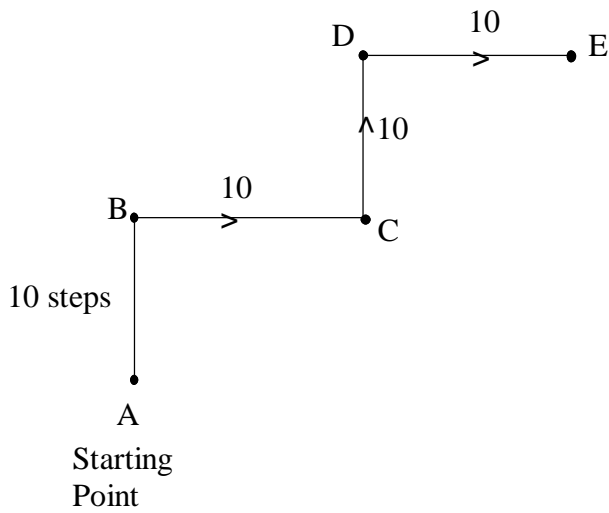
$$\Rightarrow |\vec{p}| = 1 = \sqrt{(0.2)^2 + (0.6)^2 + (a)^2}$$

On squaring both sides

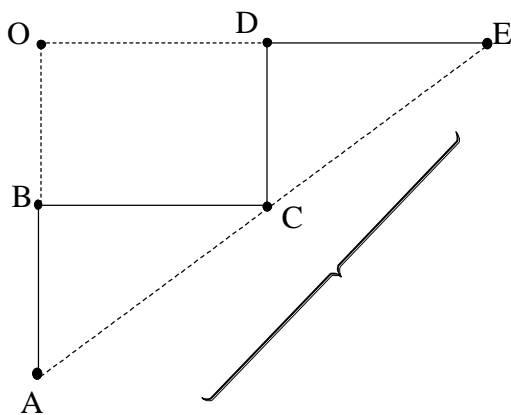
$$1^2 = 0.04 + 0.36 + a^2$$

$$1 - 0.4 = a^2 \text{ or } a = \sqrt{0.6}$$

10. (D)



(at C it u turn left. For max displacement as he should move away)
20 steps



$$AE^2 = AO^2 + OE^2$$

$$AE^2 = (20)^2 + (20)^2$$

$$AE = \sqrt{800} = 20\sqrt{2} \quad (\text{Each step is } 80 \text{ cm or } 0.8 \text{ m long})$$

$$\Rightarrow AE = 20\sqrt{2} \times 0.8 = 16\sqrt{2}$$

11. (B)

Angle between \vec{A} and \vec{B} is acute

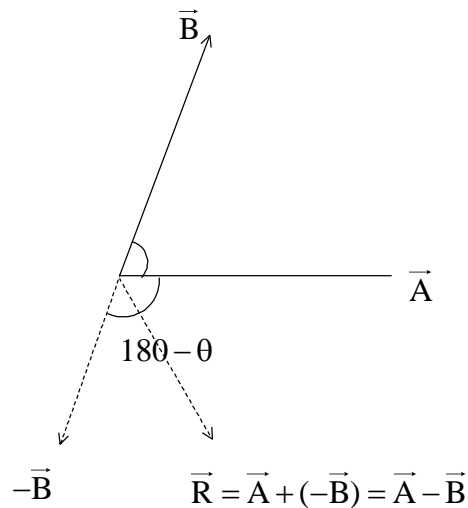
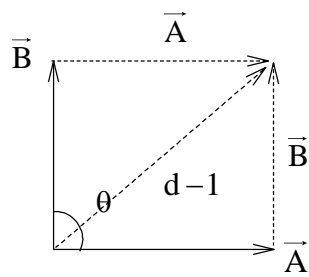
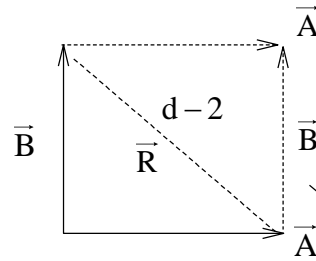


Fig - 1

Fig - 2



diagonal 1(d-1) = $\vec{A} + \vec{B}$
 \uparrow
 Major diagonal



Diagonal - 2 (d-2)
 \downarrow
 \vec{R}
 $\vec{B} + \vec{R} = \vec{A}$
 $\Rightarrow \vec{R} = \vec{A} - \vec{B}$
 \uparrow
 Minor diagonal

12. (D)

Let $\vec{R} = \vec{P} + \vec{Q}$

$\Rightarrow |\vec{P} - \vec{Q}| \leq |\vec{R}| \leq |\vec{P} + \vec{Q}|$
 $\uparrow \quad \downarrow \quad \uparrow$

When $\theta = 180^\circ$ When $\theta = 0^\circ$

R can lie anywhere between 0° and 180° both inclusive

13. (D)

When a vector is moved parallel to itself it remains same

14. (A)

$\underbrace{(\vec{A} + \vec{B}) + (\vec{A} - \vec{B})}_{= 2\vec{A}}$

As they are talking about resultant

$\Rightarrow |(\vec{A} + \vec{B}) + (\vec{A} - \vec{B})| = |2\vec{A}| = 2A$

15. (A)

For 17 N both the vector should be parallel i.e. angle between them should be zero.

For 7 N both the vectors should be antiparallel i.e. angle between them should be 180° .

For 13 N both the vectors should be perpendicular to each other i.e. angle between them should be 90° .

16. (D)

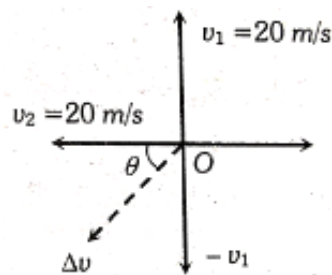
From figure

$\vec{v}_1 = 20\hat{j}$ and $\vec{v}_2 = -20\hat{j}$

$\Delta\vec{v} = \vec{v}_2 - \vec{v}_1 = -20(\hat{i} + \hat{j})$

$|\Delta\vec{v}| = 20\sqrt{2}$ and direction

$\theta = \tan^{-1}(1) = 45^\circ$ i.e. S-W



17. (C)

According to problem there should be $\sum F_x = 0$

In the given figure net force along x -axis

$$\vec{F} = 1 \cos 60^\circ \hat{i} + 2 \sin 30^\circ \hat{j} - 4 \sin 30^\circ \hat{i} = \frac{1}{2} \hat{i} + 1 \hat{j} - 2 \hat{i}$$

$$\Rightarrow \vec{F} = -\frac{1}{2} \hat{i} = -0.5 \hat{i}$$

To cancel this force minimum additional force needed is 0.5 N along the positive direction of x -axis.

18. (A)

$$\vec{P}_1 = mv \sin \theta \hat{i} - mv \cos \theta \hat{j} \text{ and } \vec{P}_2 = mv \sin \theta \hat{i} + mv \cos \theta \hat{j}$$

So, change in momentum

$$\Delta \vec{P} = \vec{P}_2 - \vec{P}_1 = 2mv \cos \theta \hat{j}, |\Delta \vec{P}| = 2mv \cos \theta.$$

19. (C)

$$R_{\max} = A + B \text{ when } \theta = 0^\circ$$

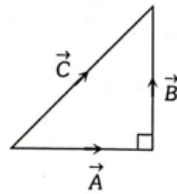
$$\therefore R_{\max} = 12 + 8 = 20 \text{ N.}$$

20. (A)

$$C = \sqrt{A^2 + B^2}$$

$$= \sqrt{3^2 + 4^2} = 5$$

\therefore Angle between \vec{A} and \vec{B} is $\frac{\pi}{2}$.



21. (A)

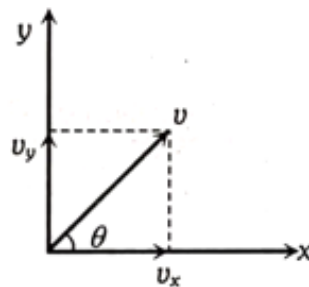
$$v_y = 20 \text{ and } v_x = 10$$

$$\therefore \text{Velocity } \vec{v} = 10 \hat{i} + 20 \hat{j}$$

Direction of velocity with x axis

$$\tan \theta = \frac{v_y}{v_x} = \frac{20}{10} = 2$$

$$\therefore \theta = \tan^{-1}(2).$$



22. (D)

$$R_{\max} = A + B = 17 \text{ when } \theta = 0^\circ$$

$$R_{\min} = A - B = 7 \text{ when } \theta = 180^\circ$$

By solving we get $A = 12$ and $B = 5$

$$\text{Now when } \theta = 90^\circ \text{ then } R = \sqrt{A^2 + B^2}$$

$$\Rightarrow R = \sqrt{(12)^2 + (5)^2} = \sqrt{169} = 13.$$

23. (C)

$$\vec{R} = \vec{S}_1 + \vec{S}_2 + \vec{S}_3$$

$$\Rightarrow R = \sqrt{12^2 + 5^2 + 6^2} = \sqrt{144 + 25 + 36} = \sqrt{205} = 14.31 \text{ m}$$

24. (D)

$$A = 3 \text{ N}, B = 2\text{N then } R = \sqrt{A^2 + B^2 + 2AB \cos \theta}$$

$$R = \sqrt{9 + 4 + 12 \cos \theta} \quad \dots\text{(i)}$$

Now $A = 6\text{N}, B = 2\text{N then}$

$$2R = \sqrt{36 + 4 + 24 \cos \theta} \quad \dots\text{(ii)}$$

From (i) and (ii) we get $\cos = -\frac{1}{2}$

$\therefore \theta = 120^\circ$.

25. (A)

$$a = \frac{|\vec{v}_f - \vec{v}_i|}{t} = \frac{\sqrt{30^2 + 40^2}}{10} = 5 \text{ m/s}^2$$

26. (A)

$$\vec{R} = 2\hat{i} + 5\hat{j} + 3\hat{k}$$

27. (D)

If $|\vec{F}_1| = F_1 = 4, |\vec{F}_2| = F_2 = 3$

And $\vec{F}_R = \vec{F}_1 + \vec{F}_2$

$$\Rightarrow 1 = |F_1 - F_2| \leq |\vec{F}_R| \leq F_1 + F_2 = 7$$

28. (B)

$$|\vec{F}_1| = 6, |\vec{F}_2| = 8$$

$$\vec{F}_R = \vec{F}_1 + \vec{F}_2$$

$$\Rightarrow |F_1 - F_2| = 2 \leq |\vec{F}_R| \leq F_1 + F_2 = 6 + 8 = 17$$

↓

Hence only possible option is B ie 11 N

29. (C)

$$\vec{F}_1 + \vec{F}_2 + \vec{F}_3 = 0$$

↑

For this always add two smaller forces.

The result of above is then added to 3rd force and then check if it can give zero

Ans. (C)

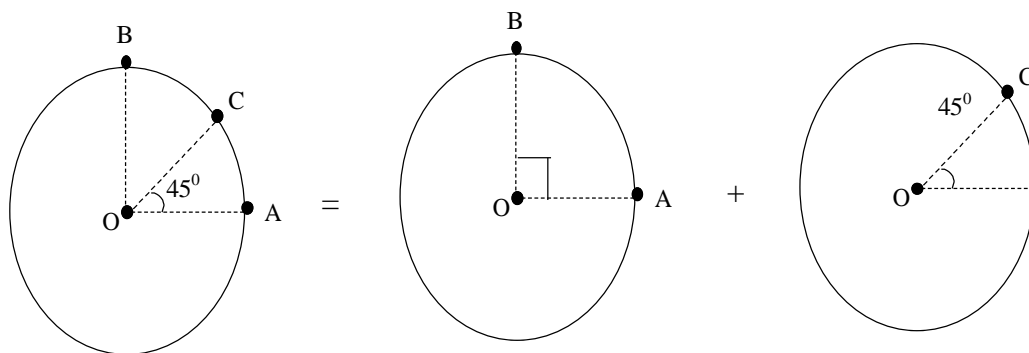
(1, 2, 1) $\Rightarrow 1+1 = 2$ (Two smaller forces)

New $2 + 2 = 4$ and $2 - 2 = 0$

↑

3rd force

30. (D)



$$\text{Let } \vec{P} = \vec{OA} + \vec{OB}$$

$$|\vec{P}| = \sqrt{R^2 + R^2 + 2(R)(R) \cos 90}$$

$$|\vec{P}| = R\sqrt{2}$$

$$\text{Angle between } \vec{A} \text{ and } \vec{P} \Rightarrow \tan \alpha = \frac{B \sin \theta}{A + B \cos \theta}$$

$$\tan \alpha = \frac{R \sin 90}{R + R \cos 90} = \frac{R}{R} = 1 \Rightarrow \alpha = 45^\circ$$

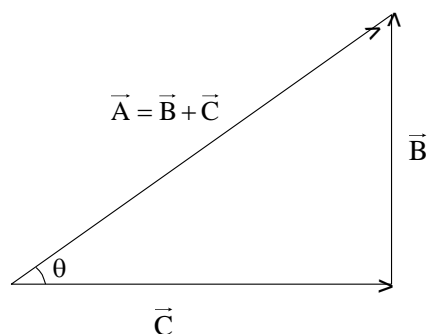
c) \vec{P} and \vec{OC} both are along same direction ie angle between them = 0°

$$\Rightarrow |\vec{P} + \vec{OC}| = R\sqrt{2} + R = R(\sqrt{2} + 1)$$

31. (A)

$$\vec{A} = \vec{B} + \vec{C}, |\vec{A}| = 5, |\vec{B}| = 4, |\vec{C}| = 3$$

Pythagoras Triplets



$$\cos \theta = \frac{|\vec{C}|}{|\vec{A}|} = \frac{3}{5} \Rightarrow \theta = \cos^{-1}\left(\frac{3}{5}\right)$$

32. (D)

$$\vec{A} + \vec{B} = \vec{A} - \vec{B}$$

$$\Rightarrow \vec{A} + \vec{B} - \vec{A} + \vec{B} = 0$$

$$2\vec{B} = 0 \text{ or } \vec{B} = 0$$

33. (B)

$$|\vec{F}_1| = F, |\vec{F}_2| = F$$

$$\text{Let } \vec{F}_R = \vec{F}_1 + \vec{F}_2 \text{ then } |\vec{F}_R| = F$$

$$\text{Given } |\vec{F}_R| = \sqrt{F_1^2 + F_2^2 + 2F_1F_2 \cos \theta}$$

$$F = \sqrt{F^2 + F^2 + 2(F)(F) \cos \theta}$$

On squaring

$$F^2 = 2F^2 + 2F^2 \cos \theta = 2F^2(1 + \cos \theta)$$

$$\Rightarrow \frac{F^2}{2F^2} = 1 + \cos \theta \text{ or } 1 + \cos \theta = \frac{1}{2}$$

$$\Rightarrow \cos \theta = \frac{1}{2} - 1 = \frac{-1}{2}$$

$$\Rightarrow \theta = 120^\circ \text{ or } 240^\circ$$

Ans θ is smaller of the two

34. (B)

$$\vec{A} = 2\hat{i} - \hat{j} + \hat{k}, \vec{B} = \hat{i} - 3\hat{j} - 5\hat{k}$$

$$\vec{C} = 3\hat{i} - 4\hat{j} - 4\hat{k} \text{ Find } |\vec{A}|, |\vec{B}| \text{ and } |\vec{C}| \text{ then use properties of } \Delta$$

Ans.: For equilateral $\Delta \Rightarrow |\vec{A}| = |\vec{B}| = |\vec{C}|$

In our case $|\vec{A}|^2 + |\vec{B}|^2 = |\vec{C}|^2$ Rt Δ

35. (B)

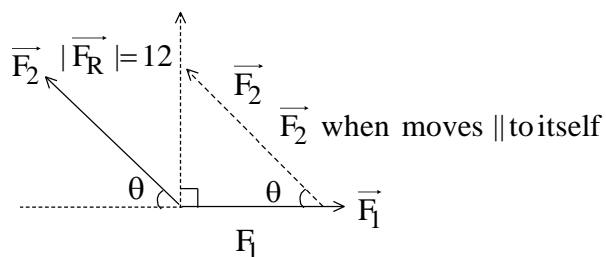
$$|\vec{F}_1| = F_1, |\vec{F}_2| = F_2 \quad (\text{Let } F_1 < F_2)$$

$$\text{Let } \vec{F}_R = \vec{F}_1 + \vec{F}_2$$

$$\text{Given } -F_1 + F_2 = 18, |\vec{F}_R| = 12$$

$$\text{And } \vec{F}_R \perp \vec{F}_1$$

$$\vec{F}_2$$



$$\text{From rt}\Delta, \tan \theta = \frac{F_R = 12}{F_1} \Rightarrow F_1 = \frac{12}{\tan \theta} = 2 \cot \theta$$

$$\sin \theta = \frac{F_R = 12}{F_2} \Rightarrow F_2 = \frac{12}{\sin \theta} = 12 \operatorname{cosec} \theta$$

$$\text{As } F_1 + F_2 = 18$$

↓

$$12 \cot \theta + 12 \operatorname{cosec} \theta = 18$$

$$12 \left[\frac{\cos \theta}{\sin \theta} + \frac{1}{\sin \theta} \right] = 18$$

$$\Rightarrow \frac{\cos \theta + 1}{\sin \theta} = \frac{3}{2}$$

$$\Rightarrow 2 \cos \theta + 12 = 3 \sin \theta$$

$$2 \cos \theta + 2 = 3 \left(\sqrt{1 - \cos^2 \theta} \right)$$

Squaring both sides $(\because \sin^2 \theta + \cos^2 \theta = 1)$

$$(2 \cos \theta + 2)^2 = \left(3\sqrt{1 - \cos^2 \theta}\right)^2$$

$$4 \cos^2 \theta + 4 + 8 \cos \theta = 9(1 - \cos^2 \theta)$$

$$4 \cos^2 \theta + 4 + 8 \cos \theta - 9 + 9 \cos^2 \theta = 0$$

$$13 \cos^2 \theta + 8 \cos \theta - 5 = 0$$

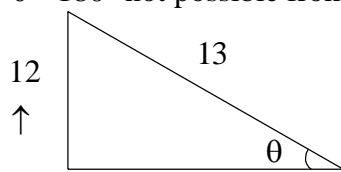
$$13 \cos^2 \theta + 13 \cos \theta - 5 \cos \theta - 5 = 0$$

$$13 \cos \theta [\cos \theta + 1] - 5(\cos \theta + 1) = 0$$

$$\Rightarrow (\cos \theta + 1)(13 \cos \theta - 5) = 0$$

$$\Rightarrow \cos \theta = -1 \text{ or } \cos \theta = \frac{5}{13}$$

$\theta = 180^\circ$ not possible from figure $\theta = \text{acute}$



5 (Pythagoras theorem)

\Rightarrow from fig.

$$\sin \theta = \frac{12}{13}$$

$$\cos \theta = \frac{5}{13}$$

$$\text{As } F_1 = 12 \cot \theta = 12 \times \frac{\cos \theta}{\sin \theta} = 12 \times \frac{5/13}{12/13}$$

$$\Rightarrow F_1 = 5$$

$$\text{As } F_2 = 12 \operatorname{cosec} \theta = \frac{12}{\sin \theta} = \frac{12}{12/13} = 13$$

36. (C)

$$\vec{A} = 2\hat{i} + 3\hat{j}, \vec{B} = \hat{i} + \hat{j}$$

Component of \vec{A} along $\vec{B} = |\hat{A}| \cos \theta \hat{B}$

$$= |\vec{A}| \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} \hat{B}$$

$$= \frac{\vec{A} \cdot \vec{B}}{|\vec{B}|} \hat{B}$$

$$= \left[\frac{(2\hat{i} + 3\hat{j}) \cdot (\hat{i} + \hat{j})}{\sqrt{1^2 + 1^2}} \right] \frac{(\hat{i} + \hat{j})}{\sqrt{1^2 + 1^2}}$$

$$= \frac{(2+3)}{\sqrt{2}} \frac{(\hat{i} + \hat{j})}{\sqrt{2}}$$

$$\text{Ans.} = \frac{5}{2} \hat{i} + \hat{j}$$

37. (C)

Given vectors can be rewritten as $\vec{A} = 2\hat{i} + 3\hat{j} + 8\hat{k}$ and $\vec{B} = -4\hat{i} + 4\hat{j} + \alpha\hat{k}$

Dot product of these vectors should be equal to zero because they are perpendicular.

$$\therefore \vec{A} \cdot \vec{B} = -8 + 12 + 8\alpha = 0 \Rightarrow 8\alpha = -4 \Rightarrow \alpha = -\frac{1}{2}.$$

38. (A)

$$\vec{A} = \hat{i} + \hat{j} + \hat{k}; \quad \vec{B} = \hat{i} + \hat{j}$$

$$\therefore A = \sqrt{1^2 + 1^2 + 1^2} = \sqrt{3}, \quad B = \sqrt{1^2 + 1^2} = \sqrt{2}$$

$$\vec{A} \cdot \vec{B} = 2$$

$$\cos \theta = \frac{\vec{A} \cdot \vec{B}}{AB} = \frac{2}{\sqrt{3}\sqrt{2}} = \left(\frac{\sqrt{2}}{\sqrt{3}} \right)$$

$$\sin \theta = \sqrt{1 - \cos^2 \theta} = \sqrt{1 - \frac{2}{3}} = \sqrt{\frac{1}{3}} = \frac{1}{\sqrt{3}}$$

$$\therefore \theta = \sin^{-1} \left(\frac{1}{\sqrt{3}} \right).$$

39. (A)

$$S = \vec{r}_2 - \vec{r}_1$$

$$\begin{aligned} W &= \vec{F} \cdot \vec{S} = (4\hat{i} + \hat{j} + 3\hat{k}) \cdot (11\hat{i} + 11\hat{j} + 15\hat{k}) \\ &= (4 \times 11 + 1 \times 11 + 3 \times 15) = 100 \text{ J.} \end{aligned}$$

40. (B)

$$\text{Let } \vec{A} \cdot (\vec{B} \times \vec{A}) = \vec{A} \cdot \vec{C}$$

Here $\vec{C} = \vec{B} \times \vec{A}$ which is perpendicular to both vector \vec{A} and \vec{B}

$$\therefore \vec{A} \cdot \vec{C} = 0.$$

41. (A)

$$\vec{L} = \vec{r} \times \vec{p} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 2 & -1 \\ 3 & 4 & -2 \end{vmatrix} = -\hat{j} - 2\hat{k}$$

i.e. the angular momentum is perpendicular to x -axis.

42. (C)

$$\vec{A} \cdot \vec{B} = 0 \quad \therefore \theta = 90^\circ.$$

43. (D)

$$\vec{P} = 2\hat{i} + b\hat{j} + 2\hat{k}$$

$$\vec{Q} = \hat{i} + \hat{j} + \hat{k}$$

Given \vec{P} is \perp^r to \vec{Q}

$$\Rightarrow \vec{P} \cdot \vec{Q} = |\vec{P}| |\vec{Q}| \cos 90 = 0$$

$$2 + b + 2 = 0 \Rightarrow b = -4$$

44. (D)

\vec{A} , \vec{B} and \vec{C} are three vectors

Concept – Vector or Dot product can be performed only between two vectors

45. (D)

Given $|\vec{A}| = |\vec{B}|$ and \vec{A} is \perp^r to \vec{B}

To find which of the following is \perp^r to $\vec{A} + \vec{B}$

(A) $\vec{A} \times \vec{B} \leftarrow$ \therefore it will give a vector \perp^r to both \vec{A} and \vec{B} i.e. \perp^r to plane of \vec{A} and \vec{B} .

(B) $\vec{A} - \vec{B} \leftarrow$ To check perform Dot product of $(\vec{A} + \vec{B}) \cdot (\vec{A} - \vec{B})$ if it is = 0 then yes.

(C) $3\vec{A} - 3\vec{B} \leftarrow$ Same as B option

(D) all of these

46. (D)

$$\vec{A} \cdot (\vec{B} \times \vec{A}) = 0$$

$\vec{A} \cdot$ gives vector \perp^r to \vec{A} and \vec{B}

Dot Product = 0 ($\therefore \theta = 90^\circ$ and $\cos 90 = 0$)

47. (A)

$$\text{Given } \vec{A} \times \vec{B} = \vec{B} \times \vec{A}$$

$$\text{We know } \vec{A} \times \vec{B} = -\vec{B} \times \vec{A}$$

$$\text{Hence } -\vec{B} \times \vec{A} = \vec{B} \times \vec{A}$$

$$\text{Or } 0 = \vec{B} \times \vec{A} + \vec{B} \times \vec{A} \text{ or } 2\vec{B} \times \vec{A} = 0$$

$$\Rightarrow \vec{B} \times \vec{A} = 0 \Rightarrow \theta = 0^\circ \text{ or } \pi$$

$$\therefore \vec{A} \neq 0, \vec{B} \neq 0$$

48. (B)

$$\vec{A} \cdot \vec{B} = |\vec{A} \times \vec{B}| \text{ given}$$

$$|\vec{A}| |\vec{B}| \cos \theta = |\vec{A}| |\vec{B}| \sin \theta$$

$$\Rightarrow \cos \theta = \sin \theta \Rightarrow \theta = 45^\circ$$

49. (A)

$$\text{Let } \vec{A} = \hat{i}, \vec{B} = \hat{i} + \hat{j} + \hat{k}$$

$$\text{Hence } \cos \theta = \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} = \frac{(\hat{i}) \cdot (\hat{i} + \hat{j} + \hat{k})}{\sqrt{1^2} \sqrt{1^2 + 1^2 + 1^2}}$$

$$\cos \theta = \frac{1}{\sqrt{1} \sqrt{3}} = \frac{1}{\sqrt{3}}$$

$$\theta = \cos^{-1} \left(\frac{1}{\sqrt{3}} \right)$$

1. (c)

$$\text{Given } |\vec{A} + \vec{B}| = |\vec{A} - \vec{B}| \times 2$$

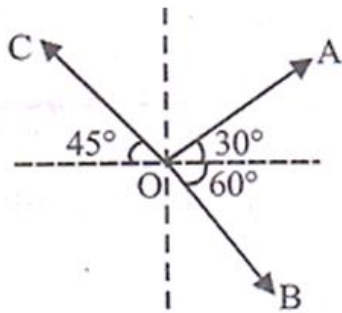
$$\Rightarrow |\vec{A} + \vec{B}|^2 = |\vec{A} - \vec{B}|^2 \times 4$$

$$\Rightarrow 0 = 3|A|^2 + 3|B|^2 - |10|A||B|\cos\theta$$

$$\Rightarrow 0 - 3|A|^2 + 3|A|^2 - |10|A|^2 \cos\theta \Rightarrow |10|A|^2 \cos\theta = 6|A|^2$$

$$\Rightarrow \cos\theta = \frac{3}{5}$$

2. (a)



Say, magnitudes of vectors is r.

$$\vec{OA} = r [\cos 30^\circ \hat{i} + \sin 30^\circ \hat{j}] = r \left[\frac{\sqrt{3}}{2} \hat{i} + \frac{1}{2} \hat{j} \right]$$

$$\vec{OC} = r [\cos 45^\circ (-\hat{i}) + \sin 45^\circ \hat{j}] = r \left[-\frac{1}{\sqrt{2}} \hat{i} + \frac{1}{\sqrt{2}} \hat{j} \right]$$

$$\vec{OB} = r [\cos 60^\circ \hat{i} - \sin 60^\circ \hat{j}] = r \left[\frac{1}{2} \hat{i} - \frac{\sqrt{3}}{2} \hat{j} \right]$$

$$\therefore \vec{OA} + \vec{OB} - \vec{OC}$$

$$= r \left[\left(\frac{\sqrt{3}+1}{2} + \frac{1}{\sqrt{2}} \right) \hat{i} + \left(\frac{1}{2} - \frac{\sqrt{3}}{2} - \frac{1}{\sqrt{2}} \right) \hat{j} \right]$$

\therefore Angle made by vector with x-axis

$$\tan^{-1} \left[\frac{\frac{1}{2} - \frac{\sqrt{3}}{2} - \frac{1}{\sqrt{2}}}{\frac{\sqrt{3}+1}{2} + \frac{1}{\sqrt{2}}} \right] = \tan^{-1} \left[\frac{1 - \sqrt{3} - \sqrt{2}}{\sqrt{3} + 1 + \sqrt{2}} \right]$$

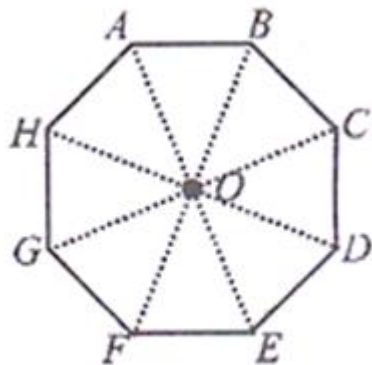
3. (d)

Projection of vector \vec{A} on vector \vec{B} is given by

$$(A \cos \theta) \hat{B} = A \left(\frac{\vec{A} \cdot \vec{B}}{AB} \right) \hat{B} = \frac{\vec{A} \cdot \vec{B}}{B} \hat{B}$$

$$= \frac{2}{\sqrt{2}} \left(\frac{\hat{i} + \hat{j}}{\sqrt{2}} \right) = \hat{i} + \hat{j}$$

4. (c)



From figure,

$$\overline{AO} + \overline{OB} = \overline{AB} \quad \overline{AO} + \overline{OC} = \overline{AC} \quad \overline{AO} + \overline{OD} = \overline{AD}$$

$$\overline{AO} + \overline{OE} = \overline{AE} \quad \overline{AO} + \overline{OF} = \overline{AF} \quad \overline{AO} + \overline{OG} = \overline{AG}$$

$$\overline{AO} + \overline{OH} = \overline{AH}$$

Now, adding we get

$$8\overline{AO} = (\overline{AB} + \overline{AC} + \overline{AD} + \overline{AE} + \overline{AF} + \overline{AG} + \overline{AH})$$

$$\Rightarrow 8(2\hat{i} + 3\hat{j} - 4\hat{k}) = \overline{AB} + \overline{AC} + \overline{AD} + \overline{AE} + \overline{AF} + \overline{AG} + \overline{AH}$$

$$\therefore \overline{AB} + \overline{AC} + \overline{AD} + \overline{AE} + \overline{AF} + \overline{AG} + \overline{AH}$$

$$= 16\hat{i} + 24\hat{j} - 32\hat{k}$$

5. (d)

Using

$$R^2 = A_1^2 + A_2^2 + 2A_1A_2 \cos \theta$$

$$5^2 = 3^2 + 5^2 + 2 \times 3 \times 5 \cos \theta \text{ or } \cos \theta = -0.3$$

$$(2\vec{A}_1 + 3\vec{A}_2) \cdot (3\vec{A}_1 - 2\vec{A}_2) = 2A_1 \times 3A_1 + (3A_2)(3A_1) \cos \theta - (2A_1)(2A_2) \cos \theta - 3A_2 \times 2A_2$$

$$= 6A_1^2 + 9A_1A_2 \cos \theta - 4A_1A_2 \cos \theta - 6A_2^2$$

$$= 6A_1^2 - 6A_2^2 + 5A_1A_2 \cos \theta$$

$$= 6 \times 3^2 - 6 \times 5^2 + 5 \times 3 \times 5 (-0.3) = -118.5$$

6. (c)

$$\text{From figure, } \vec{r}_G = \frac{a}{2}\hat{i} + \frac{a}{2}\hat{k}$$

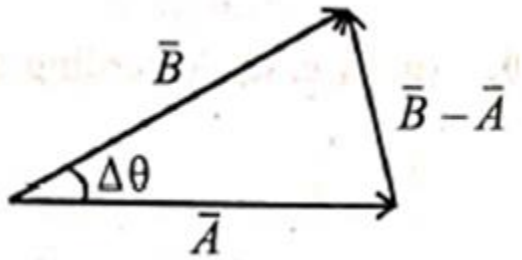
$$\vec{r}_H = \frac{a}{2}\hat{j} + \frac{a}{2}\hat{k}$$

$$\therefore \vec{r}_H - \vec{r}_G = \left(\frac{a}{2}\hat{j} + \frac{a}{2}\hat{k} \right) - \left(\frac{a}{2}\hat{i} + \frac{a}{2}\hat{k} \right) = \frac{a}{2}(\hat{j} - \hat{i})$$

7. (a)

Arc length = radius \times angle

$$\text{So, } |\vec{B} - \vec{A}| = |\vec{A}| \Delta\theta$$



$$|\vec{A}| = |\vec{B}|$$

8. (a)

$$\text{If } \vec{C} = a\hat{i} + b\hat{j} \text{ then } \vec{A} \cdot \vec{C} = \vec{A} \cdot \vec{B}$$

$$a + b = 1 \quad \dots\dots(i)$$

$$\vec{B} \cdot \vec{C} = \vec{A} \cdot \vec{B}$$

$$2a - b = 1 \quad \dots\dots(ii)$$

Solving equation (i) and (ii) we get

$$a = \frac{1}{3}, b = \frac{2}{3}$$

$$\therefore \text{ Magnitude of coplanar vector, } |\vec{C}| = \sqrt{\frac{1}{9} + \frac{4}{9}} = \sqrt{\frac{5}{9}}$$

9. (a)

$$\text{Here } \vec{P} + b\vec{R} = \vec{S} \Rightarrow \vec{R} = \frac{\vec{S} - \vec{P}}{b}$$

$$\text{Also } \vec{R} = \vec{Q} - \vec{P}$$

$$\therefore \frac{\vec{S} - \vec{P}}{b} = \vec{Q} - \vec{P} \Rightarrow \vec{S} - \vec{P} = b\vec{Q} - b\vec{P}$$

$$\therefore \vec{S} = b\vec{Q} + (1 - b)\vec{P}$$

10. (5)

$$\text{Here, } \vec{a} \cdot \vec{b} = 0$$

$$\therefore \vec{a} \cdot \vec{b} = (2\hat{i} + 4\hat{j} - 2\hat{k}) \cdot (\hat{i} + 2\hat{j} + \alpha\hat{k}) = 0$$

$$\therefore 2 \times 1 + 4 \times 2 - 2 \times \alpha = 0 \quad \therefore \alpha = 5$$

11. (2)

Given that

$$\vec{A} = (2\hat{i} + 3\hat{j} - \hat{k})m \text{ and } \vec{B} = (\hat{i} + 2\hat{j} + 2\hat{k})m$$

Component of vector \vec{A} along vector $\vec{B} = \vec{A} \cdot \hat{B}$

$$= \frac{\vec{A} \cdot \vec{B}}{|\vec{B}|} = \frac{2 + 6 - 2}{\sqrt{1^2 + 2^2 + 2^2}} \left(\because \hat{B} = \frac{\vec{B}}{|\vec{B}|} \right)$$

$$= \frac{6}{3} = 2m$$

12. (3)

Direction of particle P,

$$\hat{v}_1 = \pm \frac{\vec{A} \times \vec{B}}{|\vec{A} \times \vec{B}|} = \pm \frac{\hat{i} - \hat{j} + \hat{k}}{\sqrt{3}}$$

Direction of particle Q,

$$\hat{v}_2 = \pm \frac{\vec{A} \times \vec{C}}{|\vec{A} \times \vec{C}|} = \pm \frac{2\hat{k}}{2} = \pm \hat{k}$$

Angle between \hat{v}_1 and \hat{v}_2

$$\frac{\hat{v}_1 \cdot \hat{v}_2}{|\hat{v}_1| |\hat{v}_2|} = \frac{\pm 1}{(1)(1)} = \pm \frac{1}{\sqrt{3}}$$

Hence the angle between the direction of motion of P and Q is $\cos^{-1}\left(\frac{1}{\sqrt{3}}\right)$

\therefore value of $x = 3$

13. (180)

$\vec{P} \times \vec{Q} = \vec{Q} \times \vec{P}$ only if $\vec{P} = 0$ or $\vec{Q} = 0$

$$\Rightarrow \vec{P} \times \vec{Q} = 0$$

So, $\theta = 0^\circ$ or 180° and $0^\circ < \theta < 360^\circ$.

$\therefore \theta = 180^\circ$

14. (195)

Given: $\vec{F} = (\hat{i} + 2\hat{j} + 3\hat{k})\text{N}$

And, $\vec{r} = [(4\hat{i} + 3\hat{j} - \hat{k}) - (\hat{i} + 2\hat{j} + \hat{k})] = 3\hat{i} + \hat{j} - 2\hat{k}$

Torque, $\tau = \vec{r} \times \vec{F} = (3\hat{i} + \hat{j} - 2\hat{k}) \times (\hat{i} + 2\hat{j} + 3\hat{k})$

$$\tau = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 3 & 1 & -2 \\ 1 & 2 & 3 \end{vmatrix} = 7\hat{i} - 11\hat{j} + 5\hat{k}$$

Magnitude of torque, $|\tau| = \sqrt{195}$

15. (90)

Given,

$$|\vec{R}| = |\vec{P}| \Rightarrow |\vec{P} + \vec{Q}| = |\vec{P}|$$

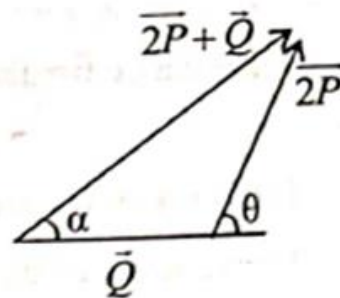
$$P^2 + Q^2 + 2PQ \cos \theta = P^2$$

$$\Rightarrow Q + 2P \cos \theta = 0$$

$$\Rightarrow \cos \theta = -\frac{Q}{2P} \quad \dots(i)$$

$$\tan \alpha = \frac{2P \sin \theta}{Q + 2P \cos \theta} = \infty (\because 2P \cos \theta + Q = 0)$$

$$\Rightarrow \alpha = 90^\circ$$



EXERCISE - 1

1. (A)

Let force be $\vec{F}_1, |\vec{F}_1| = F_1, \vec{F}_2, |\vec{F}_2| = F_2$

Let $F_1 > F_2$

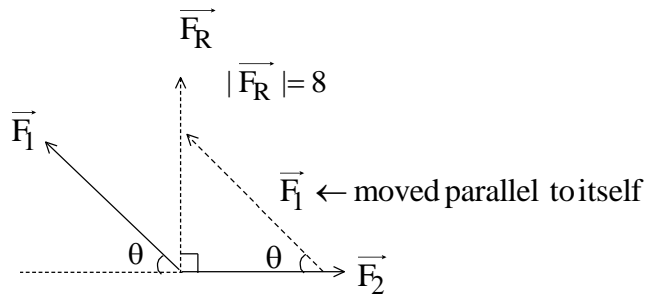
Let $\vec{F}_R = \vec{F}_1 + \vec{F}_2$

Given (i) $F_1 + F_2 = 16$

(ii) $F_R = 8$

(iii) F_R is \perp^r to $F_2 \leftarrow \perp^r$ to smaller force

$\vec{F}_R, |\vec{F}_R| = 8$



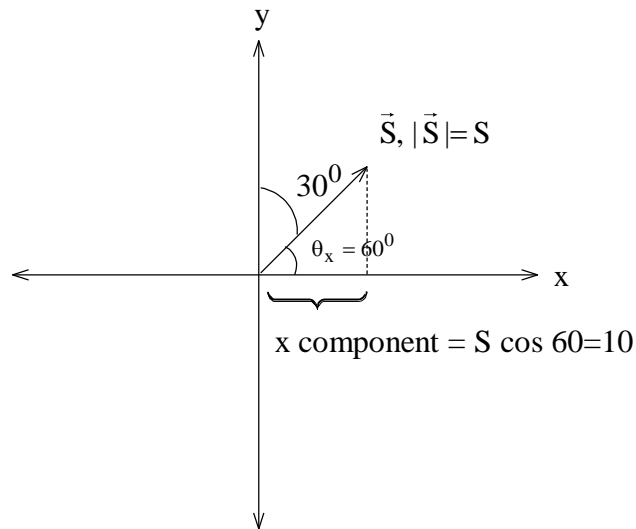
2. (D)

Component of \vec{A} along x axis = $|\vec{A}| \cos \theta_x$

Now, $|\vec{A}| \cos \theta_x$ is always $\leq |\vec{A}|$

($\because \cos \theta_x \leq 1$)

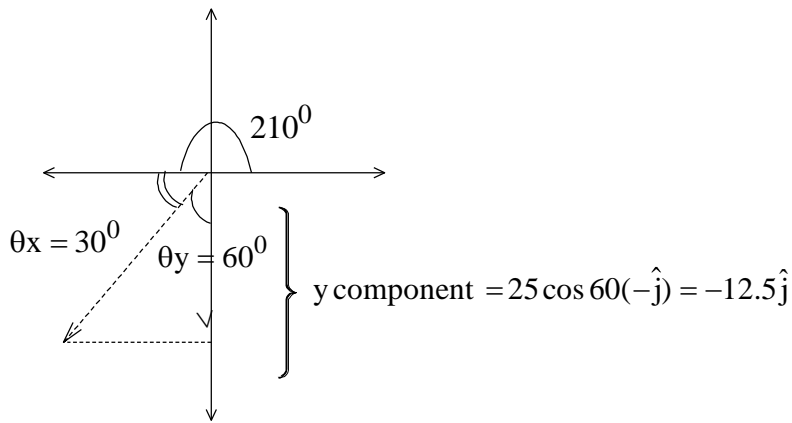
3. (D)



$$\Rightarrow S \times \frac{1}{2} = 10$$

$$S = 20$$

4. (D)



5. (B)

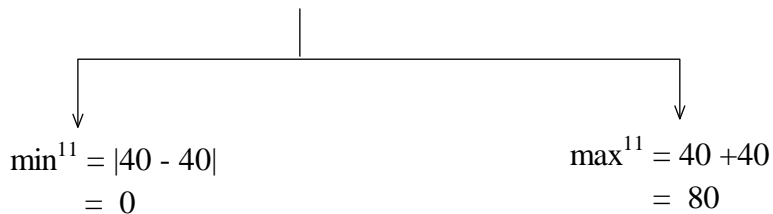
Add two smaller forces (10, 20)



Now, left forces are 30, 40,
 If we add min (10) with 30



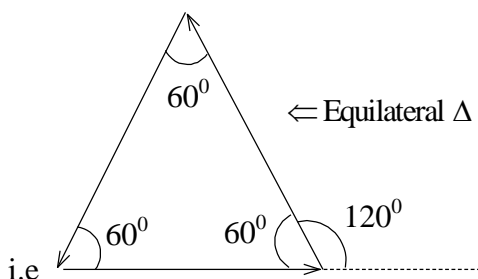
Now $\max'(=40)$ and 40 can add



B option is possible

6. (C)

Direction are along the sides of equilateral Δ taken in same order [Head of one coincides tail of another]



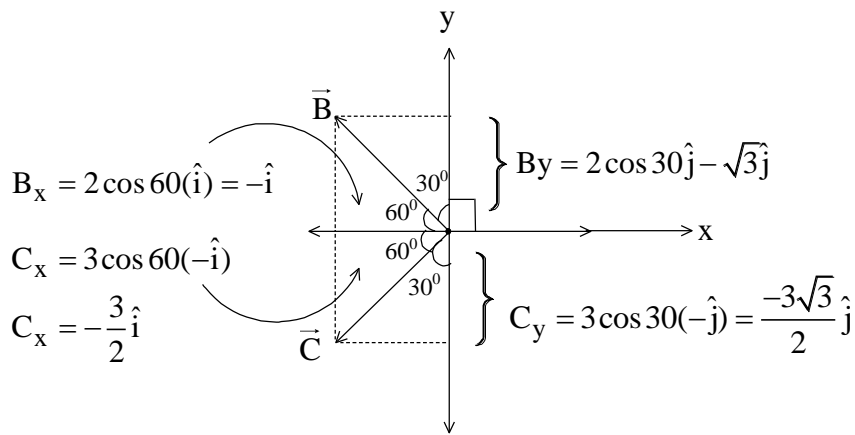
* Vector are along directions of equilateral Δ hence angle between any two $= 120^\circ$
 $(\neq 60^\circ)$

(\because angle is measured when they are joined by tails)

Let three vectors be \vec{A} , \vec{B} and \vec{C} . They each make 120° with other

And $|\vec{A}| = 1, |\vec{B}| = 2, |\vec{C}| = 3$

Lets represent them in XY plane. Lets take \vec{A} along X axis (we can take any)



From fig

* $\vec{A} = \hat{i}$ ← only along x axis with magnitude = 1

* $\vec{B} = \vec{B}_x + \vec{B}_y$

$$\vec{B} = -\hat{i} + \sqrt{3}\hat{j}$$

* $\vec{C} = \vec{C}_x + \vec{C}_y$

$$\vec{C} = \frac{-3}{2}\hat{i} - \frac{3\sqrt{3}}{2}\hat{j}$$

$$\Rightarrow \vec{A} + \vec{B} + \vec{C} = \hat{i} \left(1 - 1 - \frac{3}{2} \right) + \hat{j} \left(0 + \sqrt{3} - \frac{3\sqrt{3}}{2} \right)$$

$$\text{Let } \vec{R} = \frac{-3}{2}\hat{i} - \frac{\sqrt{3}}{2}\hat{j}$$

$$\Rightarrow |\vec{R}| = \sqrt{\left(\frac{-3}{2}\right)^2 + \left(\frac{-\sqrt{3}}{2}\right)^2}$$

$$= \sqrt{\frac{9}{4} + \frac{3}{4}}$$

$$|\vec{R}| = \sqrt{3}$$

7. (A)

In Q.6 1st vector is $\vec{A} = \hat{i}$ Resultant. Vector $\vec{R} = \frac{-3}{2}\hat{i} - \frac{\sqrt{3}}{2}\hat{j}$

Hence for angle between \vec{R} and \vec{A}

We can use

$$\cos \theta = \frac{\vec{R} \cdot \vec{A}}{|\vec{R}| |\vec{A}|}$$

$$= \frac{\left(\frac{-3}{2}\hat{i} - \frac{\sqrt{3}}{2}\hat{j} \right) \cdot (\hat{i})}{\sqrt{\left(\frac{-3}{2}\right)^2 + \left(\frac{-\sqrt{3}}{2}\right)^2} \sqrt{(1)^2}}$$

$$= \frac{-3/2}{\sqrt{\frac{9}{4} + \frac{3}{4}\sqrt{1}}} = \frac{-3}{2\sqrt{3}}$$

$$\cos \theta = \frac{-\sqrt{3} \times \sqrt{3}}{2 \times \sqrt{3}} = \frac{-\sqrt{3}}{2}$$

$$\Rightarrow \theta = 150^\circ \text{ or } 210^\circ$$

Answer should be 150° but its not given in question. Hence we'll consider 210°

8. (A)

As body can move only along y-axis

$$\Rightarrow \text{displacement } \vec{S} = 10\hat{j}$$

↓

(moves by 10m)

$$\vec{F} = -2\hat{i} + 15\hat{j} + 6\hat{k}$$

$$\text{Work Done (w)} = \vec{F} \cdot \vec{S}$$

$$= (-2\hat{i} + 15\hat{j} + 6\hat{k}) \cdot (10\hat{j})$$

$$= 150 \text{ joule}$$

9. (A)

$$\vec{A} = \hat{i} + \hat{j}, \vec{B} = \hat{i} - \hat{j}$$

We want $|\vec{c}| = 3$ and \vec{c} to be \perp^r to \vec{A} and \vec{B}

$$\text{Let } \vec{P} = \vec{A} \times \vec{B}$$

$$\vec{P} = (\hat{i} + \hat{j}) \times (\hat{i} - \hat{j})$$

$$\vec{P} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 1 & 0 \\ 1 & -1 & 0 \end{vmatrix}$$

$$= \hat{i}(0-0) - \hat{j}(0-0) + \hat{k}(-1-1)$$

$$\vec{P} = -2\hat{k}$$

So, \vec{P} is \perp^r to \vec{A} and \vec{B} from definition of cross product

$$\vec{c} = 3(\hat{P})$$

We want is magnitude to be 3 and direction \perp^r to \vec{A} and \vec{B} that's why 3 times (\hat{p}) ← magnitude = 1

direction \perp^r to \vec{A} and \vec{B}

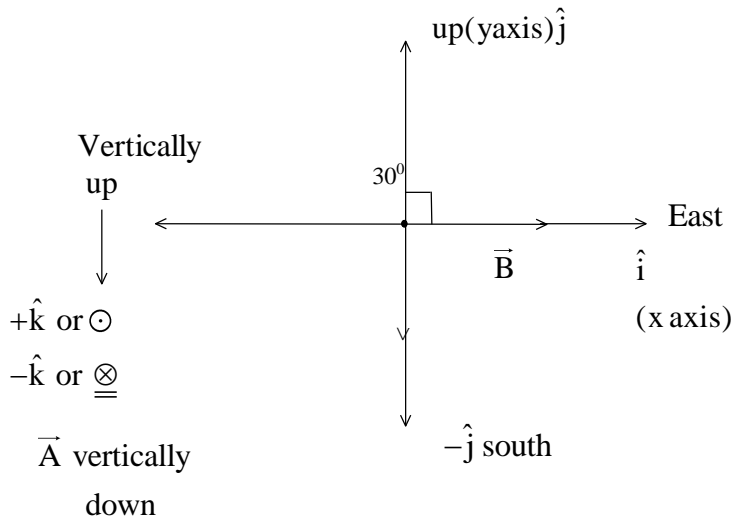
$$\vec{c} = 3 \frac{(-2\hat{k})}{\sqrt{(-2)^2}} = \frac{-6\hat{k}}{2} = -3\hat{k}$$

If we perform $\vec{B} \times \vec{A}$ then we'll get $\vec{C} = +3\hat{k}$

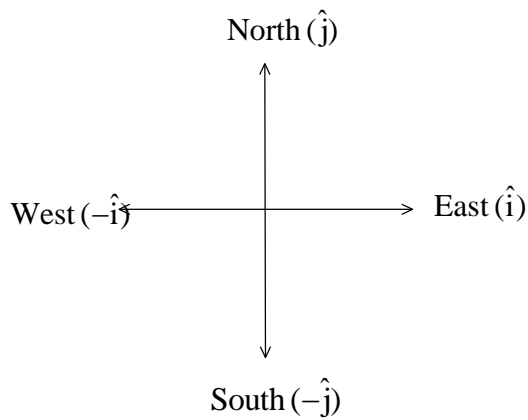
$$\vec{A} \times \vec{B} = -\hat{k} \times \hat{i}$$

$$= -\hat{j}$$

10. (D)



11. (B)



Initial Velocity $\vec{u} = 5\hat{i}$

Final velocity $\vec{v} = 5\hat{j}$

$$\Rightarrow \Delta\vec{v} = \vec{V}_f - \vec{V}_i = \vec{v} - \vec{u} = 5\hat{j} - 5\hat{i}$$

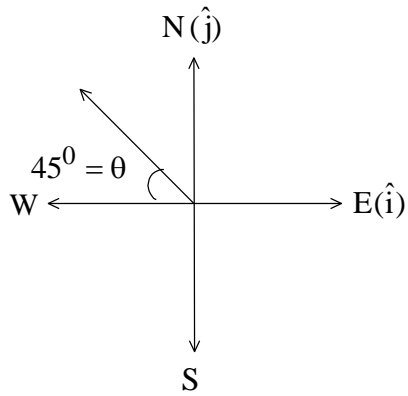
$$\Rightarrow \vec{a} = \frac{\Delta\vec{v}}{t} = \frac{5\hat{j} - 5\hat{i}}{10} = \frac{(-\hat{i} - \hat{j})}{2}$$

$$\vec{a} = -\frac{1}{2}\hat{i} + \frac{1}{2}\hat{j}$$

$$\Rightarrow |\vec{a}| = \sqrt{\left(\frac{-1}{2}\right)^2 + \left(\frac{1}{2}\right)^2} = \sqrt{\frac{2}{4}} = \frac{1}{\sqrt{2}}$$

$$|\vec{a}| = \frac{1}{\sqrt{2}}$$

$$\vec{a} = -\frac{1}{2}\hat{i} + \frac{1}{2}\hat{j}$$



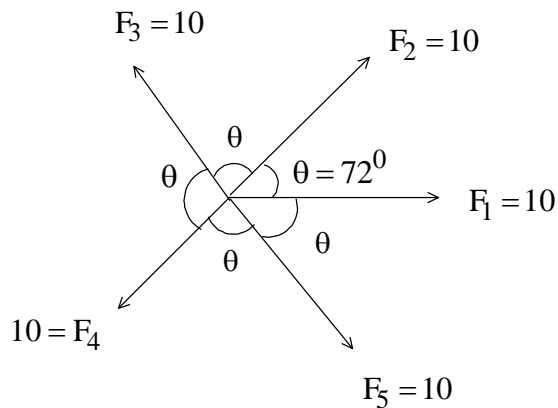
-ve x and +ve y, \vec{a} lies along
 \Rightarrow B option North west

When magnitude of x component and y component are equal then $\theta = 45^\circ$ always.

\therefore from fig $\tan \theta = \frac{\text{y component}}{\text{x component}} = 1$

$\Rightarrow \theta = 45^\circ$

12. (A)



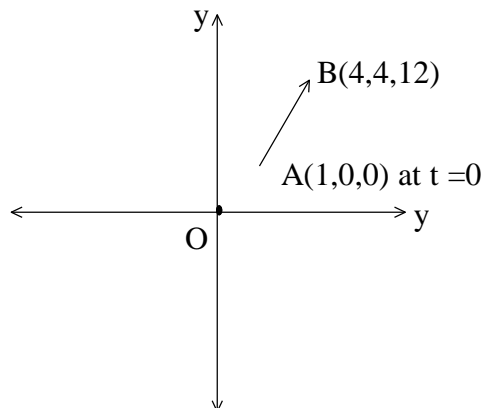
$\vec{F}_1 + \vec{F}_2 + \vec{F}_3 + \vec{F}_4 + \vec{F}_5 = 0$

Note

When force of equal magnitude using in same plane acts at a point such that angle between any two adjacent is equal. Then these form regular closed polygon.

As polygon is closed. Hence $\vec{F} = 0$ net

13. (D)



Direction of motion is A to B ie = AB

$$\begin{aligned}\vec{AB} &= (4-1)\hat{i} + (4-0)\hat{j} + (12-0)\hat{k} \\ &= 3\hat{i} + 4\hat{j} + 12\hat{k} \\ &= 3\hat{i} + 4\hat{j} + 12\hat{k} \\ \Rightarrow AB &= \frac{|\vec{AB}|}{|\vec{AB}|} = \frac{3\hat{i} + 4\hat{j} + 12\hat{k}}{\sqrt{3^2 + 4^2 + 12^2}} = \frac{\sqrt{169}}{13} = 13 \\ \Rightarrow \vec{AB} &= \frac{3\hat{i} + 4\hat{j} + 12\hat{k}}{13}\end{aligned}$$

Velocity $= |\vec{v}|$ and direction AB

$$\begin{aligned}&= 65 \\ &= 5 \frac{(3\hat{i} + 4\hat{j} + 12\hat{k})}{13}\end{aligned}$$

$$\vec{v} = 15\hat{i} + 20\hat{j} + 60\hat{k}$$

Displacement $\vec{S} = \text{velocity } (\vec{v}) \times \text{time}$

$$\vec{S} = 2(15\hat{i} + 20\hat{j} + 60\hat{k})$$

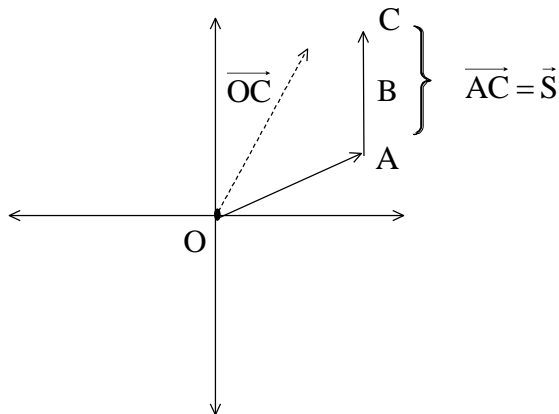
$$\vec{S} = 30\hat{i} + 40\hat{j} + 60\hat{k}$$

Displacement wrt to point A

Hence position vector $= \vec{OA} + \vec{S}$

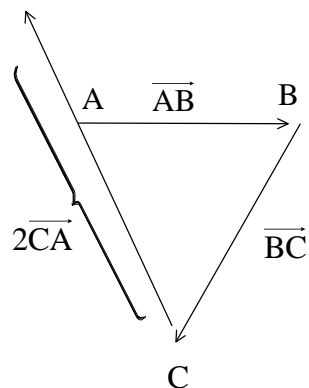
$$(i + 0j + 0k) + (30\hat{i} + 40\hat{j} + 120\hat{k})$$

$$= 31\hat{i} + 40\hat{j} + 120\hat{k}$$



$$\text{Position} = \vec{OC} = 31\hat{i} + 40\hat{j} + 120\hat{k}$$

14. (A)



$$\vec{AB} + \vec{BC} = \vec{AC} \text{ from and low AB}$$

$$\Rightarrow \underbrace{\overrightarrow{AB} + \overrightarrow{BC}}_{\overrightarrow{AC}} + 2\overrightarrow{CA} = \underbrace{\overrightarrow{AC} + 2\overrightarrow{CA}}_{\overrightarrow{CA}}$$

$$\begin{aligned} \therefore \overrightarrow{AC} &= -\overrightarrow{CA} \\ &= \overrightarrow{CA} \end{aligned}$$

15. (C)

$$\text{Let } |\overrightarrow{F_1}| = 3P, |\overrightarrow{F_2}| = 2P$$

$$\text{Let } \overrightarrow{F_R} = \overrightarrow{F_1} + \overrightarrow{F_2}$$

$$\Rightarrow |\overrightarrow{F_R}| = R$$

$$|\overrightarrow{F_R}| = \sqrt{F_1^2 + F_2^2 + 2F_1F_2 \cos \theta}$$

$$R = \sqrt{(3P)^2 + (2P)^2 + 2(3P)(2P) \cos \theta}$$

$$R = \sqrt{3P^2 + 4P^2 + 12P^2 \cos \theta}$$

Squaring both sides

$$R^2 = 13P^2 + 12P^2 \cos \theta$$

$$\text{Now if } |\overrightarrow{F_1}| = 2(3P) = 6P$$

$$\Rightarrow |\overrightarrow{F_R}| = 2(R) = 2R$$

$$|\overrightarrow{F_2}| = 2P \text{ remains same}$$

$$|\overrightarrow{F_R}| = \sqrt{F_1^2 + F_2^2 + 2F_1F_2 \cos \theta}$$

$$2R = \sqrt{(6P)^2 + (2P)^2 + 2(6P)(2P) \cos \theta}$$

Squaring both sides

$$4R^2 = 36P^2 + 4P^2 + 24P^2 \cos \theta$$

$$\Rightarrow 4R^2 = 40P^2 + 24P^2 \cos \theta$$

From equation

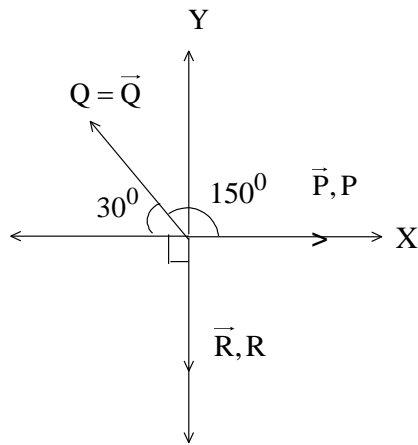
$$4[13P^2 + 12P^2 \cos \theta] = 4(10P^2 + 6P^2 \cos \theta)$$

$$6P^2 \cos \theta = -3P^2$$

$$\Rightarrow \cos \theta = -\frac{1}{2}$$

$$\text{Or } \theta = 120^\circ \text{ or } 240^\circ$$

16. (D)



Resolve \vec{P}, \vec{Q} and \vec{R} along X and Y axis

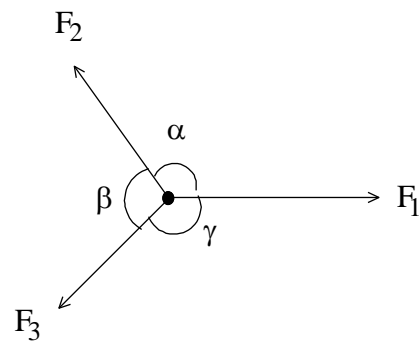
And $\vec{P} + \vec{Q} + \vec{R} = 0 \leftarrow \therefore$ they are in equilibrium

Solve to get relation between P, Q and R

Alternate method \rightarrow Lami's theorem

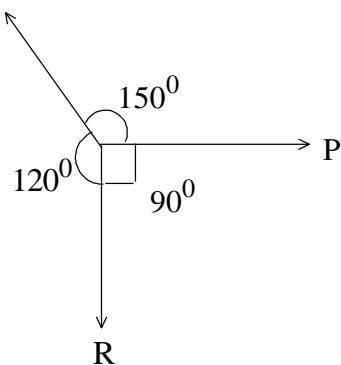
Valid only when 3 vectors add to give resultant = 0

Given



If $\vec{F}_1 + \vec{F}_2 + \vec{F}_3 = 0$ then from lami's theorem

Q



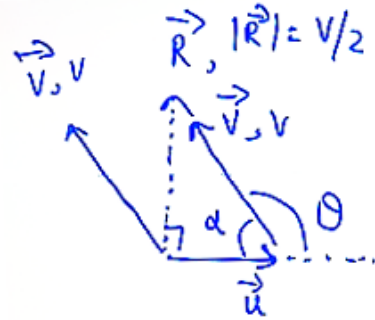
From lami's theorem

$$\frac{P}{\sin 120} = \frac{Q}{\sin 90} = \frac{R}{\sin 150} = K$$

$$\left. \begin{aligned} \Rightarrow P &= K \sin 120 = \frac{K\sqrt{3}}{2} \\ \Rightarrow Q &= K \sin 90 = k \\ \Rightarrow R &= K \sin 150 = \frac{k}{2} \end{aligned} \right\} P:Q:R = \sqrt{3}:2:1$$

17. (D)

Let $\vec{R} = \vec{u} + \vec{v}$ and \vec{R} is \perp^r to \vec{u}



$$\sin \alpha = \frac{V/2}{V} = \frac{1}{2}$$

$$\alpha = 30^\circ$$

$$\Rightarrow \theta = 180 - \alpha = 150^\circ$$

18. (B)

let $\vec{R} = \vec{P} + \vec{Q}$

$$\Rightarrow R_{\min} = |\vec{P} - \vec{Q}|$$

It will be 0 (zero)

If $P = Q$

19. (B)

$|\vec{F}_1| = 6, |\vec{F}_2| = 8$, let $\vec{F}_R = \vec{F}_1 + \vec{F}_2$

$$|\vec{F}_1 - \vec{F}_2| \leq |\vec{F}_R| \leq |\vec{F}_1 + \vec{F}_2|$$

$$|-2| \leq F_R \leq 14$$

$$2 \leq F_R \leq 14$$

Ans. (B)

20. (D)

$$6 = |2 - 8| \leq |\vec{R}| \leq (2 + 8) = 10$$

4 doesn't lie between 6 and 10

21. (A)

$$\vec{A} = \hat{i} + 2\hat{j} + 2\hat{k}$$

$$\vec{B} = 2\hat{i} + \hat{j} + 2\hat{k}$$

Projection of \vec{B} on $\vec{A} = |\vec{B}| \cos \theta \hat{A}$

$$= |\vec{B}| \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} \hat{A}$$

$$= \left[\frac{(\hat{i} + 2\hat{j} + 2\hat{k}) \cdot (2\hat{i} + \hat{j} + 2\hat{k})}{\sqrt{1^2 + 2^2 + 2^2}} \right] \frac{\vec{A}}{|\vec{A}|}$$

$$= \left(\frac{2 + 2 + 4}{\sqrt{9}} \right) \frac{(\hat{i} + 2\hat{j} + 2\hat{k})}{\sqrt{1^2 + 2^2 + 2^2}} = \frac{8}{9} (\hat{i} + 2\hat{j} + 2\hat{k})$$

EXERCISE - 2

1. (A, D)

$$\vec{A} = 3\hat{i} + 4\hat{j}, \vec{B} = \hat{i} + \hat{j}$$

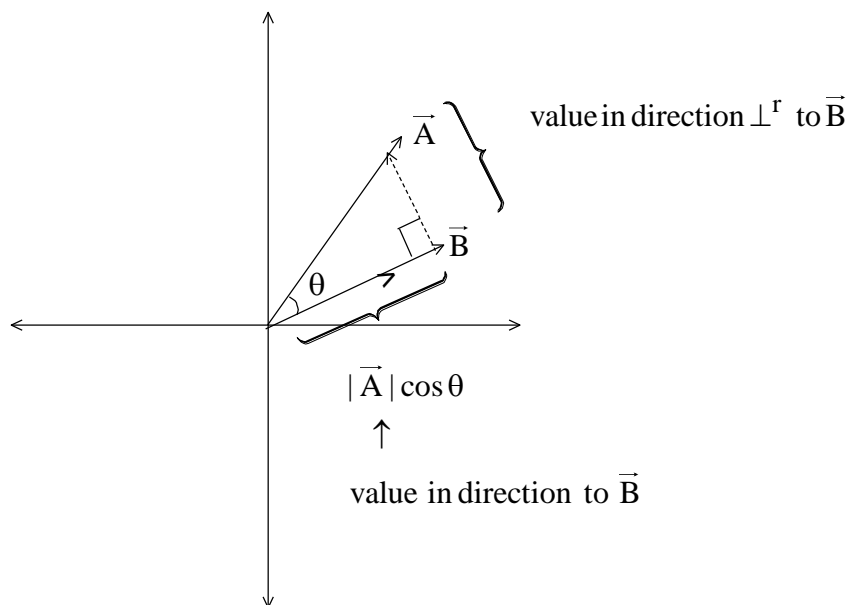
θ = angle between \vec{A} and \vec{B}

Component of \vec{A} along $\vec{B} = |\vec{A}| \cos \theta \hat{B}$

$$= |\vec{A}| \cos \theta \hat{B} = |\vec{A}| \cos \theta \frac{\vec{B}}{|\vec{B}|}$$

$$|\vec{A}| \cos \theta \frac{(\hat{i} + \hat{j})}{\sqrt{1^2 + 1^2}}$$

$$|\vec{A}| \cos \theta \frac{(\hat{i} + \hat{j})}{\sqrt{2}}$$



We can apply Δ law in our figure

$$\Rightarrow \vec{A} = \vec{A}_{\text{along } \vec{B}} + \vec{A}_{\perp \text{ to } \vec{B}}$$

Learn always valid

As $\vec{A}_{\text{along } \vec{B}} = |\vec{A}| \cos \theta \hat{B}$

$$|\vec{A}| \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} \frac{\vec{B}}{|\vec{B}|}$$

$$= \frac{(\vec{A} \cdot \vec{B})(\vec{B})}{|\vec{B}|^2}$$

$$= \frac{(3\hat{i} + 4\hat{j}) \cdot (\hat{i} + \hat{j})(\hat{i} + \hat{j})}{[\sqrt{1^2 + 1^2}]^2}$$

$$\vec{A}_{\text{along } \vec{B}} = \frac{(3+4)}{2} \hat{i} + \hat{j} = \frac{7}{2}(\hat{i} + \hat{j})$$

As $\vec{A} = \vec{A}_{\text{along } \vec{B}} + \vec{A}_{\perp \text{ to } \vec{B}}$

$$\Rightarrow \vec{A}_{\perp \text{ to } \vec{B}} = \vec{A} - \vec{A}_{\text{along } \vec{B}}$$

$$\begin{aligned}
&= (3\hat{i} + 4\hat{j}) - \frac{7}{2}(\hat{i} + \hat{j}) \\
&= \frac{6\hat{i} + 8\hat{j} - 7\hat{i} - 7\hat{j}}{2} \\
&\Rightarrow \vec{A} \perp^r \text{ to } \vec{B} = \frac{-\hat{i} + \hat{j}}{2}
\end{aligned}$$

Lets convert the above expression in given options form.

Clearly two options are possible B and D

B is incorrect as for B direction is $\frac{\hat{i} - \hat{j}}{2}$

* And direction of $\vec{A} \perp^r$ to \vec{B} is $\frac{-\hat{i} + \hat{j}}{2}$

* For D option we have to check as direction matches

$$(D) \vec{A} \perp^r \text{ to } \vec{B} = |\vec{A}| \sin \theta \left(\frac{\hat{j} - \hat{i}}{\sqrt{2}} \right)$$

$$|\vec{A}| = \sqrt{3^2 + 4^2} = 5$$

$$\sin \theta = \frac{|\vec{A} \times \vec{B}|}{|\vec{A}| |\vec{B}|} \left[\because |\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin \theta \right]$$

$$\Rightarrow \vec{A} \times \vec{B} = 3(\hat{i} \times \hat{i}) + 3(\hat{i} \times \hat{j}) + 4(\hat{j} \times \hat{i}) + 4(\hat{j} \times \hat{j})$$

$$\qquad \qquad \qquad 0 \qquad \hat{k} \qquad -\hat{k} \qquad 0$$

$$\vec{A} \times \vec{B} = 3\hat{k} - 4\hat{k} = -\hat{k}$$

$$\Rightarrow |\vec{A} \times \vec{B}| = 1$$

$$\Rightarrow \sin \theta = \frac{|\vec{A} \times \vec{B}|}{|\vec{A}| |\vec{B}|} = \frac{1}{5\sqrt{2}}$$

$$\Rightarrow D \text{ option} = |\vec{A}| \sin \theta \left(\frac{\hat{j} - \hat{i}}{\sqrt{2}} \right)$$

$$\cancel{5} \frac{1}{\cancel{5}\sqrt{2}} \left[\frac{\hat{j} - \hat{i}}{\sqrt{2}} \right]$$

$$D \text{ option} = \frac{-\hat{i} + \hat{j}}{\sqrt{2}} = \vec{A} \perp^r \text{ to } \vec{B}$$

Ans - A, D

2. (A, B, C)

$\vec{A} = 2\hat{i} + \hat{j} + \hat{k}$ $\vec{B} = \hat{i} + \hat{j} + \hat{k}$ then unit vector.

(i) First check which options are not unit vector and eliminate them

In out case all are unit vector (ii) solve options

$$(A) \perp^r \text{ to } \vec{A} \text{ is } \frac{-\hat{j} + \hat{k}}{\sqrt{2}}$$

$$\Rightarrow A. \frac{-\hat{j} + \hat{k}}{\sqrt{2}} \text{ must be } = 0$$

$$(2\hat{i} + \hat{j} + \hat{k}) \cdot \left(\frac{-\hat{j} + \hat{k}}{\sqrt{2}} \right) = \frac{(0-1+1)}{\sqrt{2}} = 0$$

\Rightarrow A is correct

(B) Parallel to \vec{A} is $\frac{2\hat{i} + \hat{j} + \hat{k}}{\sqrt{6}}$

Apply condition for which are ||

i.e. $\frac{A_x}{B_x} = \frac{A_y}{B_y} = \frac{A_z}{B_z}$

In our case $\frac{A_x = 2}{B_x = \frac{2}{\sqrt{6}}} = \frac{A_y = 1}{B_y = \frac{1}{\sqrt{6}}} = \frac{A_z = 1}{B_z = \frac{1}{\sqrt{6}}} = \sqrt{6}$

Condition satisfies \Rightarrow B is correct

(C) \perp^r to \vec{B} is $\frac{-\hat{j} + \hat{k}}{\sqrt{2}}$

$\Rightarrow \vec{B} \cdot \left[\frac{-\hat{j} + \hat{k}}{\sqrt{2}} \right]$ must be =0

$(\hat{i} + \hat{j} + \hat{k}) \cdot \left[\frac{-\hat{j} + \hat{k}}{\sqrt{2}} \right] = \frac{0-1+1}{\sqrt{2}} = 0$

\Rightarrow C option is correct

(D) In correct

\therefore condition doesn't satisfy

$$\left[\frac{A_x}{B_x} = \frac{A_y}{B_y} = \frac{A_z}{B_z} \right]$$

Ans : A, B, C

3. (B, D)

If $(\vec{V}_1 + \vec{V}_2)$ is \perp^r to $(\vec{V}_1 - \vec{V}_2)$

Dot product is zero $\therefore \theta = 90^\circ$

$$\Rightarrow [\vec{V}_1 + \vec{V}_2] \cdot [\vec{V}_1 - \vec{V}_2] = 0$$

$$\vec{V}_1 \cdot \vec{V}_1 - \vec{V}_1 \cdot \vec{V}_2 + \vec{V}_2 \cdot \vec{V}_1 - \vec{V}_2 \cdot \vec{V}_2 = 0$$

$$\Rightarrow |\vec{V}_1|^2 - |\vec{V}_2|^2 = 0$$

$$\Rightarrow |\vec{V}_1|^2 = |\vec{V}_2|^2 \text{ or } |\vec{V}_1| = |\vec{V}_2|$$

(A) Not necessary

(B) Derived

(C) Not possible

(D) yes they can have any angle between them

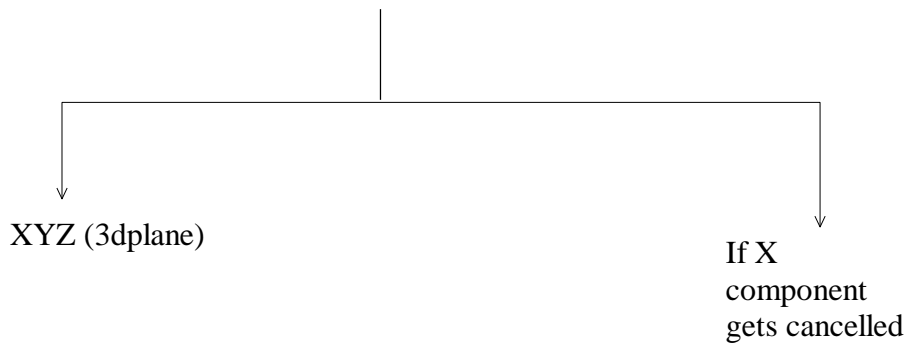
4. (A, D)

\vec{A} and \vec{B} lie in one plane \leftarrow let it be xy plane

\vec{C} lies in different plane \leftarrow cant be XY

Let it be XZ plane

Hence $\vec{A} + \vec{B} + \vec{C}$ will be a vector which can lie only in



- (A) can't be zero
 (D) XYZ or YZ is different from XY and XZ

5. (A, C)
 Dot or cross product is performed between 2 vectors

(A) $\vec{u} \cdot (\vec{v} \times \vec{w})$

$\vec{u} \cdot$ [cross product hence it u be a vector]

(B) $(\vec{u} \cdot \vec{v}) \cdot \vec{w}$

scalar $\cdot \vec{w}$ not possible

(C) $(\vec{u} \cdot \vec{v}) \cdot \vec{w}$

scalar (\vec{w}) possible no dot or cross product

(D) $\vec{u} \times (\vec{v} \cdot \vec{w})$

$\vec{u} \cdot$ (scalar)

Not possible

6. (B, C)

Given $|\vec{A} \cdot \vec{B}| = (\pm 8) = |\vec{A}| |\vec{B}| \cos \theta$

$|\vec{A} \times \vec{B}| = 8\sqrt{3} = |\vec{A}| |\vec{B}| \sin \theta$

$\Rightarrow \frac{|\vec{A} \times \vec{B}|}{|\vec{A} \cdot \vec{B}|} = \frac{|\vec{A}| |\vec{B}| \sin \theta}{|\vec{A}| |\vec{B}| \cos \theta} = \pm \sqrt{3}$

$\tan \theta = \pm \sqrt{3}$

$\Rightarrow \theta = 60^\circ \text{ or } 120^\circ$

7. (A, C, D)

(B) Incorrect as on changing orientation of axis, the given vector will make different angle wrt new axis hence component will change.

8. (A, B, D)

Let $\vec{A} = A_x \hat{i} + A_y \hat{j} \Rightarrow |\vec{A}| = \sqrt{A_x^2 + A_y^2}$

$\vec{B} = B_x \hat{i} + B_y \hat{j} \Rightarrow |\vec{B}| = \sqrt{B_x^2 + B_y^2}$

$$\vec{R} = \vec{A} + \vec{B} = \underbrace{(A_x + B_x)}_{R_x} \hat{i} + \underbrace{(A_y + B_y)}_{R_y} \hat{j}$$

(A) $R_x = A_x + B_x$

(B) $R_x = A_x + B_x \leq |\vec{A}| + |\vec{B}|$

Equal to when $A_y = B_y = 0$

(C) Proved from B

(D) Prove from B

9. (B, C, D)

$$|\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin \theta$$

And $\sin \theta \leq 1$ always

$$\Rightarrow X \text{ (a) } |\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin \theta \leq |\vec{A}| |\vec{B}|$$

(b) for $\sin \theta = 1$

(c) for $\sin \theta < 1$

(d) for $\sin \theta = 0$

EXERCISE - 3

1. (I) \rightarrow A, (II) \rightarrow A, (III) \rightarrow D, (IV) \rightarrow C

$$\vec{A} = 4\hat{i} + 4\hat{j}, \vec{B} = 4\hat{i} - 4\hat{j}$$

Column A

(i) $|\vec{A} + \vec{B}| = |4\hat{i} + 4\hat{j} + 4\hat{i} - 4\hat{j}| = |8\hat{i}| = 8$

(ii) $|\vec{A} - \vec{B}| = |4\hat{i} + 4\hat{j} - (4\hat{i} - 4\hat{j})| = |8\hat{j}| = 8$

(iii) $\vec{A} \cdot \vec{B} = (4\hat{i} + 4\hat{j}) \cdot (4\hat{i} - 4\hat{j}) = 16 - 16 = 0$

(iv) $|\vec{A} \times \vec{B}| = |(4\hat{i} + 4\hat{j}) \times (4\hat{i} - 4\hat{j})|$
 $= |16\hat{i} \times \hat{i} - 16\hat{i} \times \hat{j} + 16\hat{j} \times \hat{i} + 16\hat{j} \times \hat{j}|$
 $= |32\hat{k}|$
 $= 32$

Ans. I \rightarrow A, II \rightarrow A, III \rightarrow D, IV \rightarrow C

2. (I) \rightarrow D, (II) \rightarrow A, (III) \rightarrow C, (IV) \rightarrow C

$$|\vec{A}| = 1, |\vec{B}| = 2, \theta \text{ between } \vec{A} \text{ and } \vec{B} = 90^\circ$$

Column A

(i) $\vec{A} \cdot \vec{B} = 0$ [$\because \theta = 90 \Rightarrow \cos 90 = 0$] A

(ii) $|\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin 90$
 $= (1)(2)(1)$
 $= 2$

(iii) $|\vec{A} + \vec{B}| = \sqrt{A^2 + B^2 + 2AB \cos 0}$
 $= \sqrt{1^2 + 2^2 + 2(1)(2)(1)}$
 $= \sqrt{5}$

(iv) $|\vec{A} - \vec{B}| = \sqrt{A^2 + B^2 - 2AB \cos 90}$

$$= \sqrt{1^2 + 2^2 - 0}$$

$$= \sqrt{5}$$

Ans. I → D, II → A, III → C, IV → C

EXERCISE - 4

1. Dot and cross product can occur between 2 vectors only
 * Scalar can't be added to vector using above two points
 Ans → C, D, F, H (only)

2. $\vec{F} = q(\vec{V} \times \vec{B})$

(A) $\left. \begin{array}{l} \vec{V} = -\hat{i} \\ \vec{B} = \hat{j} \end{array} \right\} \vec{V} \times \vec{B} = -\hat{i} \times \hat{j} = -\hat{k}$

(B) $\left. \begin{array}{l} \vec{V} = \hat{j} \\ \vec{B} = \hat{j} \end{array} \right\} \vec{V} \times \vec{B} = \hat{j} \times \hat{j} = 0 \text{ no direction}$

(C) $\left. \begin{array}{l} \vec{V} = -\hat{j} \\ \vec{B} = \hat{k} \end{array} \right\} \vec{V} \times \vec{B} = -\hat{j} \times \hat{k} = -\hat{i}$

3. $\vec{A} = 5\hat{i} + 4\hat{j} - 6\hat{k}$

$\vec{B} = -2\hat{i} + 2\hat{j} + 3\hat{k}$

$\vec{C} = 4\hat{i} + 3\hat{j} + 2\hat{k}$

a) $\vec{R} = \vec{A} - \vec{B} + \vec{C}$

$\vec{R} = 1\hat{i} + 5\hat{j} - 7\hat{k}$

b) $\cos \theta_z = \frac{R_z}{|\vec{R}|} = \frac{-7}{\sqrt{11^2 + 5^2 + (-7)^2}}$

They have asked angle wrt +z hence value with sign is substituted.

$\Rightarrow \theta_z = \cos^{-1} \left[\frac{-7}{\sqrt{195}} \right]$

c) magnitude of \vec{A} along $\vec{B} = |\vec{A}| \cos \theta$

$\Rightarrow |\vec{A}| \cos \theta = \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|}$

$= \frac{\vec{A} \cdot \vec{B}}{|\vec{B}|} = \frac{(5\hat{i} + 4\hat{j} - 6\hat{k}) \cdot (-2\hat{i} + 2\hat{j} + 3\hat{k})}{\sqrt{(-2)^2 + (2)^2 + (3)^2}}$

$= \frac{-10 + 8 - 18}{\sqrt{17}} = \frac{-20}{\sqrt{17}}$

4. $\vec{A} = 3\hat{i} + 5\hat{j}$ $\vec{B} = 2\hat{i} + 4\hat{j}$

(a) $\vec{A} \times \vec{B} = (3\hat{i} + 5\hat{j}) \times (2\hat{i} + 4\hat{j})$

$= 6\hat{i} \times \hat{i} + 12\hat{i} \times \hat{j} + 10\hat{j} \times \hat{i} + 20\hat{j} \times \hat{j}$

$\begin{matrix} 0 & & & 0 \end{matrix}$

$$12\hat{k} - 10\hat{k} = 2\hat{k}$$

(b) $\vec{A} \cdot \vec{B} = (3\hat{i} + 5\hat{j}) \cdot (2\hat{i} + 4\hat{j})$
 $= 6 + 20 = 26$

(c) $(\vec{A} + \vec{B}) \cdot \vec{B} = (5\hat{i} + 9\hat{j}) \cdot (2\hat{i} + 4\hat{j})$
 $= 10 + 36 = 46$

(d) magnitude of \vec{A} along $\vec{B} = |\vec{A}| \cos \theta$

$$|\vec{A}| \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|} = \frac{\vec{A} \cdot \vec{B}}{|\vec{B}|} = \frac{26}{\sqrt{2^2 + 4^2}} = \frac{26}{\sqrt{20}}$$

$$= \frac{26 \times 13}{2\sqrt{5}} = \frac{13}{\sqrt{5}}$$

5. $\vec{A} = 3\hat{i} + 3\hat{j} - 2\hat{k}$

$$\vec{B} = -\hat{i} - 4\hat{j} + 2\hat{k}$$

$$\vec{C} = 2\hat{i} + 2\hat{j} + \hat{k}$$

(a) $\vec{A} \cdot (\vec{B} \times \vec{C})$

$$\vec{B} \times \vec{C} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -1 & -4 & 2 \\ 2 & 2 & 1 \end{vmatrix}$$

$$= \hat{i}(-4 - 4) - \hat{j}(-1 - 4) + \hat{k}(-2 + 8)$$

$$\vec{B} \times \vec{C} = -8\hat{i} + 5\hat{j} + 6\hat{k}$$

$$\Rightarrow \vec{A} \cdot (\vec{B} \times \vec{C}) = (3\hat{i} + 3\hat{j} - 2\hat{k}) \cdot (-8\hat{i} + 5\hat{j} + 6\hat{k})$$

$$= -24 + 15 - 12$$

$$= -21$$

(b) $\vec{A} \cdot (\vec{B} + \vec{C}) = (3\hat{i} + 3\hat{j} - 2\hat{k}) \cdot (\hat{i} - 2\hat{j} + 3\hat{k})$

$$= 3 - 6 - 6 = 9$$

(c) $\vec{a} \times (\vec{b} + \vec{c})$

$$= (3\hat{i} + 3\hat{j} - 2\hat{k}) \times (\hat{i} - 2\hat{j} + 3\hat{k})$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 3 & 3 & -2 \\ 1 & -2 & 3 \end{vmatrix}$$

$$= \hat{i}(9 - 4) - \hat{j}(9 + 2) + \hat{k}(-6 - 3)$$

$$= 5\hat{i} - 11\hat{j} - 9\hat{k}$$

6. Let $\vec{B} = B_x\hat{i} + B_y\hat{j} + B_z\hat{k}$

Given $|\vec{B}| = 8$

Given \vec{A} lies along X axis $\Rightarrow \vec{A} = A_x\hat{i}$

Also $\vec{A} + \vec{B} = \vec{C}$ it lies along y axis and $|\vec{C}| = 2|\vec{A}|$

Let $\vec{C} = C_y\hat{j}$

Hence $|\vec{C}| = C_y = 2|\vec{A}| = 2A_x$

$$\text{i.e } C_y = 2A_x \quad \dots(1)$$

$$\vec{A} + \vec{B} = (A_x + B_x)\hat{i} + B_y\hat{j} + B_z\hat{k}$$

$$\vec{C} = C_y\hat{j} = 2A_x\hat{j} \quad (\because C_y = 2A_x)$$

$$\Rightarrow 2A_x\hat{j} = (A_x + B_x)\hat{i} + B_y\hat{j} + B_z\hat{k} \text{ on comparing}$$

$$A_x + B_x = 0 \quad (\leftarrow \text{from } \hat{i})$$

$$\Rightarrow A_x = -B_x \quad \dots\dots(2)$$

$$* 2A_x = B_y \quad \dots\dots(3) \text{ (from } \hat{j} \text{)}$$

$$* 0 = B_z \quad \dots\dots(4) \text{ (from } \hat{k} \text{)}$$

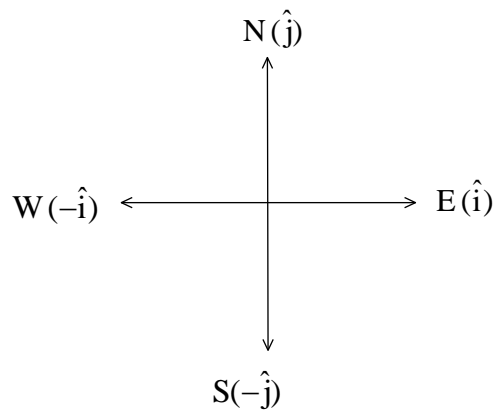
$$\text{As } |\vec{B}| = \sqrt{B_x^2 + B_y^2 + B_z^2}$$

$$8 = \sqrt{(-A_x)^2 + (2A_x)^2 + (0)^2}$$

$$8 = \sqrt{5A_x^2} = A_x\sqrt{5}$$

$$\Rightarrow A_x = \frac{8}{\sqrt{5}}$$

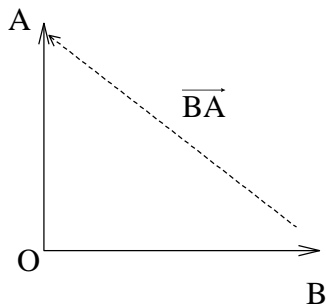
7.



$$\vec{OA} = 120\text{km North} = 120\hat{j}$$

$$\vec{OB} = 100 \text{ km due east} = 100\hat{i}$$

$$\vec{BA} = ?$$



$$\text{Using } \Delta \text{ law } \vec{OB} + \vec{BA} = \vec{OA}$$

$$\Rightarrow \vec{BA} = \vec{OA} - \vec{OB}$$

$$= 120\hat{j} - 100\hat{i}$$

$$8. \quad \vec{A} - \vec{B} = 2\vec{C} \quad \dots(1)$$

$$\vec{A} + \vec{B} = 4\vec{C} \quad \dots(2)$$

*equation (1) and (2)

$$\vec{A} - \vec{B} + \vec{A} + \vec{B} = 2\vec{C} + 4\vec{C}$$

$$2\vec{A} = 6\vec{C} \Rightarrow \vec{A} = 3\vec{C}$$

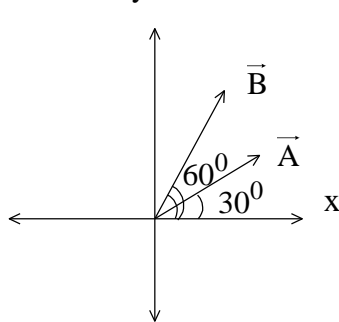
$$\text{ie } \vec{A} = 3(3\hat{i} - 4\hat{j}) = 9\hat{i} + 12\hat{j}$$

$$\vec{A} + \vec{B} - (\vec{A} - \vec{B}) = 4\vec{C} - 2\vec{C}$$

$$\Rightarrow 2\vec{B} = 2\vec{C}$$

$$\Rightarrow \vec{B} = \vec{C} = 3\hat{i} + 4\hat{j}$$

$$9. \quad |\vec{A}| = |\vec{B}| = 10$$



$$a \Rightarrow A_x = 10 \cos 30^\circ \hat{i} = 5\sqrt{3}\hat{i}$$

$$A_y = 10 \sin 30^\circ \hat{j} = 5\hat{j}$$

$$\Rightarrow B_x = 10 \cos 60^\circ \hat{i} = 5\hat{i}$$

$$B_y = 10 \sin 60^\circ \hat{j} = 5\sqrt{3}\hat{j}$$

$$\Rightarrow \vec{A} + \vec{B} = 5(\sqrt{3} + 1)\hat{i} + 5(1 + \sqrt{3})\hat{j}$$

$$= 5(\sqrt{3} + 1)(\hat{i} + \hat{j})$$

$$10. \quad |\vec{v}| = 50 \text{ m/s}$$

Direction of velocity is along \vec{AB}

$$\Rightarrow \vec{V} = |\vec{V}| \frac{\vec{AB}}{|\vec{AB}|}$$

$$\vec{AB} = 7\hat{i} + 24\hat{j} \Rightarrow |\vec{AB}| = \sqrt{7^2 + (24)^2} = 25$$

$$\Rightarrow \vec{V} = 50 \frac{(7\hat{i} + 24\hat{j})}{25}$$

$$= 14\hat{i} + 48\hat{j}$$

$$11. \quad |\vec{A}| = A, |\vec{B}| = B \text{ and let } A > B$$

$$\Rightarrow A - B = 17 \quad \dots(1) \text{ given opposite direction}$$

If \vec{A} is \perp^r to \vec{B} and $\vec{R} = \vec{A} + \vec{B}$ then $|\vec{R}| = 25$

$$|\vec{R}| = \sqrt{A^2 + B^2 + 2AB \cos 90^\circ}$$

$$25 = \sqrt{A^2 + B^2} \Rightarrow A^2 + B^2 = (25)^2 = 625$$

Solve (1) and (2)

12. (A) No \rightarrow eg current
 (B) (i) No \rightarrow for two vectors resultant to be zero they should be equal in magnitude and opposite in direction
 (ii) yes \rightarrow 3 vectors can add to zero. They need not have same magnitude

$$\left. \begin{array}{l} A = 3\hat{i} \\ B = -2\hat{i} \\ C = -\hat{i} \end{array} \right\} \vec{A} + \vec{B} + \vec{C} = 0$$

- (C) To solve such question assume some magnitude of vectors.

let $|\vec{A}| = 3, |\vec{B}| = 4$

As $\vec{R} = \vec{A} + \vec{B}$

$\Rightarrow 1 = |A - B| \leq |\vec{R}| \leq A + B = 7$

So $|\vec{R}|$ can be $1 \leq |\vec{A}|$ and $|\vec{B}|$

(D) $\vec{c} = \vec{a} + \vec{b}$

$$\Rightarrow |a - b| \leq |\vec{c}| \leq a + b$$

\uparrow when $\theta = 180^\circ$ \uparrow $\theta = 0^\circ$
 between \vec{A} and \vec{B}

So if $|\vec{C}| = |\vec{A}| + |\vec{B}| \Rightarrow \vec{A}$ is \parallel to \vec{B} (collinear)

- (E) $|\vec{a}| \neq 0$ and $|\vec{b}| \neq 0$

Given $|\vec{a} + \vec{b}| = |\vec{a} - \vec{b}|$

$$\sqrt{a^2 + b^2 + 2ab \cos \theta} = \sqrt{a^2 + b^2 - 2ab \cos \theta}$$

$$\Rightarrow a^2 + b^2 + 2ab \cos \theta = a^2 + b^2 - 2ab \cos \theta$$

$$\Rightarrow 4ab \cos \theta = 0$$

$$\Rightarrow \cos \theta = 0 \text{ as } a \neq 0 \text{ and } b \neq 0$$

$$\Rightarrow \theta = 90^\circ$$

- (F) Time t doesn't have direction

(G) $\vec{a} \times \vec{b} = \vec{a} \cdot \vec{b}$

Vector Scalar

Not possible

- (H) No \rightarrow As they only denote direction

13. $|\vec{A}| = 2, |\vec{B}| = 3, \theta = 60^\circ$ between \vec{A} and \vec{B}

(a) $\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos(\theta = 60^\circ)$

$$= (2)(3) \frac{1}{2}$$

$$= 3$$

(b) $|\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin \theta$

$$= (2)(3) \frac{\sqrt{3}}{2}$$

$$= 3\sqrt{3}$$

14. (2.00)

$$\text{Given: } |\vec{A} + \vec{B}| = \sqrt{3} |\vec{A} - \vec{B}|$$

$$\therefore |a\hat{i} + a\cos\omega t\hat{i} + a\sin\omega t\hat{j}| = \sqrt{3} |a\hat{i} - a\cos\omega t\hat{i} - a\sin\omega t\hat{j}|$$

$$\Rightarrow |(1 + \cos\omega t)\hat{i} + \sin\omega t\hat{j}| = \sqrt{3} |(1 - \cos\omega t)\hat{i} - \sin\omega t\hat{j}|$$

$$\sqrt{2 + 2\cos\omega t} = \sqrt{3}\sqrt{2 - 2\cos\omega t}$$

$$\therefore 1 + \cos\omega t = 3(1 - \cos\omega t)$$

$$\Rightarrow 4\cos\omega t = 2 \quad \therefore \cos\omega t = \frac{1}{2} \text{ or } \omega t = \frac{\pi}{3}$$

$$\therefore \frac{\pi}{6} \times \tau = \frac{\pi}{3} \quad \therefore \tau = 2.00 \text{ seconds}$$